NATIONAL ADVISORY COMMITTEE FOR AERONAUTICS

TECHNICAL NOTE 4005

AN EXPERIMENTAL INVESTIGATION OF THE EFFECT OF VARIOUS
PARAMETERS INCLUDING TIP MACH NUMBER ON THE FLUTTER
OF SOME MODEL HELICOPTER ROTOR BLADES

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SUMMARY

Experimental studies were made to evaluate some of the effects of parameters such as Mach number, blade angle, and structural damping on the flutter of model helicopter rotor blades in the hovering condition. The model blades had NACA 23012 and 23018 airfoil sections and each was tested at chordwise center-of-gravity locations of approximately 27.5 and 37 percent chord. Data were obtained at test-medium densities ranging from 0.0012 to 0.0030 slug per cubic foot and at various pitch angles up into the stall. Mixtures of air and Freon-12 were used for the test medium in order to extend the tip Mach number range of the tests to slightly above unity.

Forward movement of the blade chordwise center-of-gravity location generally raised the flutter speeds at low pitch angles but had no appreciable effect at high pitch angles. An increase in the structural damping generally raised the flutter speed at high pitch angles. At a given pitch angle, the flutter occurred at essentially constant dynamic pressure for variations in density. A large beneficial effect of Mach number was observed near the section critical Mach number and was such that if flutter did not occur up to a tip Mach number of 0.73, it would not occur at all. Out of these studies a criterion is tentatively advanced which indicates design requirements for completely flutter-free operation of helicopter blades.

The significant flutter data for a large number of tests along with detailed descriptions of the models are included in tabular form to facilitate more detailed analyses of the results presented.

INTRODUCTION

The possibility of rotor-blade flutter exists for some helicopters of current and future types which are designed to operate at high tip

¹Supersedes declassified NACA Research Memorandum L53D24 by George W. Brooks and John E. Baker, 1953.

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speeds without being completely mass balanced about the blade 1/4 chord at all spanwise positions (ref. 1). Although the general characteristics of the flutter of propeller blades and wings in subsonic compressible flows at pitch angles up to and including the stall region have been studied by several investigators (e.g., refs. 2 and 3), no studies of similar nature have been reported in regard to helicopter blades. Theoretical methods are available which may be used to estimate the classical flutter speeds of helicopter blades in incompressible flows (refs. 4 and 5), but as yet neither theoretical nor experimental data have been presented for the prediction of the effects of compressibility or blade stall. In consideration of the differences between helicopter and propeller blades as to rigidity, structural damping, radius-to-chord ratio, solidity, root fixity, airfoil section, and so forth, some doubt exists as to the applicability of wing or propeller. blade flutter data to the prediction of the flutter characteristics of helicopter blades.

As a part of a general investigation of helicopter flutter, the present program was initiated in an effort to determine the effects of various parameters including Mach number, structural damping, and chordwise center-of-gravity location on flutter of model helicopter blades at zero forward velocity. The models had flapping hinges and plan forms representative of full-scale helicopter blades.

A portion of this investigation is devoted to the definition of a stall-flutter criterion for the design of helicopter blades which can be operated flutter-free throughout the pitch-angle range at all subsonic blade tip Mach numbers. Inasmuch as blade twisting deformations affect the blade pitch angle at flutter, and since the subject of blade twist may be of some general interest, a brief study of blade twist including the effects of Mach number is included.

SYMBOLS

a	slope of lift curve, $dc_1/d\alpha$
ъ	blade half-chord, ft
c	speed of sound in testing medium, ft/sec
cl	section lift coefficient
<u>c_1</u>	mean section lift coefficient
EI	blade bending stiffness, lb-in. ²
GJ	blade torsional stiffness, lb-in.2

g _h 1	structural damping coefficient for first elastic bending mode
e _{h2}	structural damping coefficient for second elastic bending mode
$\mathbf{g}_{\mathbf{C}}$	structural damping coefficient for first torsion mode
I_{α}	blade mass moment of inertia about elastic axis, slug-ft ² /ft
1,	mass moment of inertia of blade including blade shank about flapping hinge, slug-ft ²
Ir	mass moment of inertia of blade shank about flapping hinge, $slug-ft^2$
m	blade mass per unit length, slugs/ft
m _r	mass of blade shank, slugs
М	rotational Mach number
д	dynamic pressure, lb/sq ft
r _a ²	nondimensional radius of gyration of blade section about elastic axis, I_{α}/mb^2
R	rotor radius, ft
v	section speed, fps
x _{eg}	section center-of-gravity location, percent chord
x _{EA}	section elastic-axis location, percent chord
α	angle of attack, deg
γ	mass constant of rotor blade, $2b\rho aR^4/I_1$
1/ĸ	blade mass-density ratio, $m/\pi \rho b^2$
θ	blade pitch angle between chord line and plane of rotation, deg
Δθ	measured blade twist, deg

ρ	density	of	testing	medium,	slugs/	cu	ft
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- σ rotor solidity, 2b/πR
- ω_f flutter frequency, radians/sec
- whl experimental nonrotating natural frequency for first elastic flapwise bending mode, radians/sec
- wh2 experimental nonrotating natural frequency for second elastic flapwise bending mode, radians/sec
- experimental nonrotating natural frequency for first torsion mode, radians/sec

Subscripts:

- o standard atmosphere
- 0.8R 0.8 rotor radius
- t blade tip
- c corrected for aerodynamic and dynamic twist
- s initial setting
- cr critical value

Notation for test rotor blades:

- (f) forward chordwise center-of-gravity location
- (r) rearward chordwise center-of-gravity location

APPARATUS AND TEST METHODS

The experimental investigations of helicopter-rotor-blade flutter reported herein were conducted in the Langley vacuum sphere (ref. 2). This facility consists of a steel tank in which is mounted a 500 horse-power electric motor which is used to whirl the rotor assemblies. The sphere can be evacuated to provide different air densities; or it can be filled with Freon-12 gas, or mixtures of air and Freon-12, at various densities. The combined use of air and Freon-12 provides a means for studying independently the effects of Mach number and velocity on flutter.

Blade configuration. The blades used in the tests were designed to be geometrically representative of normal helicopter configurations, and to flutter at speeds which would yield useful data at Mach numbers where compressibility effects might become important over a range of pitch angles and chordwise center-of-gravity locations. The blades were of composite wood construction with a stainless-steel rod (spar) embedded in the wood and extending longitudinally along the quarter-chord line. Three holes extending parallel to the main spar were routed in the blades, one at each of the following points: 6.25, 50, and 62.5 percent chord, as shown in figure 1. The chordwise center-of-gravity position was varied by means of selective location of stainless-steel rods or inserts in these holes. The structural damping of the blades was varied in some cases by wrapping these rods with cloth.

The blades studied had NACA 23012 sections with chordwise center-of-gravity locations of 27.5 and 37.3 percent chord, and NACA 23018 sections with chordwise center-of-gravity locations of 28.0 and 36.5 percent chord. The rotor assembly including the blade, blade shank, hub, and counterweights is shown in figure 2. The blades were tested as one-blade configurations and the active portion of the blade extended from a radius of 8 inches to a radius of 46 inches with a flapping hinge located at a radius of 2.5 inches. No drag hinges were used. The centrifugal forces were balanced by adjustable counterweights.

The blade dimensions, natural frequencies, and other pertinent flutter parameters are given in table I. The frequencies were measured with the blades mounted on the hub in the test condition, that is, free to flap. The blades are grouped according to airfoil section, blades 1 to 5 having NACA 23012 airfoil sections and blades 6 to 9 having NACA 23018 airfoil sections. During the tests, blade 2 was observed to have warped slightly, resulting in an upward deflection of the trailing edge. Models 1, 2, 3, and 4 were separate blades. Blade 5 was obtained by wrapping the rods of blade 4 with cloth to increase the structural damping. This also resulted in an increase in torsional stiffness. Models 6 and 7 were also separate blades. The rods of blade 7 were wrapped with cloth as previously mentioned. This modification resulted in a blade having two new values of the torsional structural damping coefficient; one value for low-amplitude vibrations and another for high-amplitude vibrations. These new configurations are referred to as blade 8 and blade 9, respectively. The blade numbers are accompanied by the letters (f) and (r) which are used to designate forward and rearward chordwise center-of-gravity locations, respectively.

Instrumentation and data observations. - Flutter data were obtained through the use of wire strain gages cemented to the blades in such a way as to indicate both torsional and bending deflections, figure 2. The strain-gage outputs together with a tachometer signal for measuring the rotational speed were recorded on oscillograph records such as shown

in figure 3. The end of the blade was illuminated instantaneously at a predetermined point in each revolution by means of a strobolight energized through a contactor on the motor shaft. The image of the blade tip, thus obtained, was used to measure the pitch angles at the blade tip by use of a telescope with the eyepiece graduated for angular measurements. The pitch-angle measurements were then used to determine the amount of blade twist for various test conditions.

Flutter testing procedure. The blades were operated with the pitch angle fixed at the blade root. The pitch angle was changed between tests to obtain data over a range of pitch angles from about 8° to 30°. The operating procedure for each flutter test consisted of slowly increasing the speed of the test blade until strong flutter was first encountered, at which point an oscillograph record was taken. The pitch angle at the blade tip was then measured at a slightly lower speed (40 to 80 rpm lower) in order to have the blade in a more stable condition. The flutter region was often penetrated, in attempting to find an upper boundary, until either the flutter became too severe or the flutter region was traversed. In the latter case, a record was taken upon reentering the flutter region from the top.

The effect of Mach number on the flutter characteristics was studied by use of various mixtures of Freon-12 gas (sound speed approximately equal to 500 fps) and air at various densities ranging from 0.0012 to 0.0030 slug per cubic foot. The blades were initially fluttered in air at various densities after which they were tested in nearly pure Freon-12 gas. The percentage of Freon-12 was then lowered by steps, thus raising the sound speed of the mixture until the desired range of sound speed had been covered. Flutter data were obtained at various densities for each mixture by variation of the absolute pressure of the testing medium. As a result of the flutter tests being made in the aforementioned gaseous mediums over a relatively wide range of velocities, tip Mach numbers up to 1.1 could be reached, and the Reynolds number at the blade tip for the tests varied from about 125,000 to about 2,250,000.

RESULTS AND DISCUSSION

General Considerations

Flutter parameters and reference stations. The flutter data are presented as functions of the flutter speed coefficient $V/b\omega_{C}$, a design parameter $b\omega_{C}/c$, the tip Mach number M_{t} , the density ratio ρ/ρ_{O} , and the pitch angle θ . In some instances, the data are also presented in terms of combinations of these parameters, for example, $(V/b\omega_{C})\sqrt{\rho/\rho_{O}}$.

The significance of these parameters in propeller-blade and wing stall flutter studies is recognized and discussed in some detail in references 2 and 3.

The flutter speed coefficient as well as the blade pitch angles and pitch-angle settings are referred to the station at 0.8R; however, the Mach number and measured blade twist are referred to the blade tip. These reference stations were chosen because (1) the velocity of the element at 0.8 blade radius appears to be more representative for flutter than the element at 0.75 radius which is usually referred to in helicopter analyses, (2) the tip Mach number readily identifies the Mach number at any radial location, and (3) the twist at the tip is the measured twist.

Lift coefficient. In order to facilitate the estimation of the blade loading at flutter, figure 4 shows the mean section lift coefficient as a function of the pitch angle as calculated by means of reference 6 for an element located at the 0.8 blade radius assuming this station to be typical. Inasmuch as the lift curves for NACA 23012 and 23018 airfoil sections are not appreciably different, a mean value of the slope of the lift curve is assumed and a single mean-value curve of $\overline{c_1}$ plotted against θ is presented for the representation of both blades.

Presentation of Flutter Data

The significant parameters for the blades tested are given in table I and discussed in the previous section entitled apparatus and test methods. The detailed results of the flutter investigation are tabulated in table II, according to blade section, blade number, and chordwise center-of-gravity location. The general sequence of presentation corresponds closely to the order in which the data were taken.

Some of the general trends determined during the investigation are discussed in the following paragraphs with the aid of samples of data presented in figures 5 to 16. The presentation of the flutter results is divided into two parts: the first relating to data taken at Mach numbers where compressibility effects were found to be insignificant, and the second relating to the effects of Mach number and the effects of various flutter parameters at Mach numbers where compressibility effects appeared to be important.

In addition to the experimental flutter investigation, a limited study was made to determine blade twist as influenced by dynamic pressure, flutter and divergence, and Mach number. The results of this study are presented in the appendix and in table III and are discussed with the aid of figures 17 to 21.

Discussion of the Effects of Various Parameters

on Flutter at Low Mach Numbers

Blade pitch angle. The general shapes of the characteristic flutter curves obtained for propeller blades and wings in essentially incompressibile flows by plotting the flutter speed coefficient as a function of the blade pitch angle or angle of attack have been established by the work of several investigators (e.g., refs. 2 and 3). Figures 5 to 8 of this paper present some experimental results of a similar nature obtained for some model helicopter blades which show the characteristic shapes of the flutter curves as well as the effect of various flutter parameters.

The flutter data for a typical blade are shown in figure 5 where both the flutter speed coefficient and the ratio of the flutter frequency to blade first natural torsional frequency are plotted as a function of blade pitch angle. The curve of flutter speed coefficient, or flutter curve, separates the stable and unstable regions; the unstable region being above the flutter curve. As the blade pitch angle is increased, the flutter speed coefficient drops slightly at first and then rapidly as the blade apparently begins to stall. As the pitch angle is further increased, the flutter speed coefficient decreases until some minimum value is reached. Further increases in pitch angle result in a rather sharp rise in the flutter speed coefficient, possibly due to a rearward shift in center of pressure arising from blade stall. The curve of frequency ratio shows that a reduction in the value of the flutter speed coefficient is accompanied by an increase in flutter frequency.

The upper portion of the flutter curve, corresponding to low pitch angles, defines the region of classical flutter whereas the lower portion of the curve defines the region of stall flutter. Classical flutter usually involves a coupling of blade motion in at least two degrees of freedom. Since flutter occurs in the mode representing minimum potential, the significant modes for conventional helicopter blades are probably blade torsion and flapping. As shown by the frequency-ratio curve of figure 5, the classical flutter occurs at a frequency considerably lower than the first torsion natural frequency. Stall flutter on the other hand is a predominantly torsional oscillation, the frequency of which is shown by figure 5 to be very nearly equal to the first torsional natural frequency. Some flutter of the wake-excited type (see ref. 7) was also obtained. This flutter occurred at pitch-angle settings near 0°, at speeds of the order of 85 percent of the classical flutter speed, and at frequency ratios of the order

of
$$\frac{\omega_f}{\omega_{r}} = 0.80$$
.

Now that the characteristic shape of the flutter curve for a typical blade is established, the following paragraphs along with figures 6 to 9 will be devoted to an analysis of the effects of various flutter parameters. The absence of data at low pitch angles is due to the fact that the blades were designed so that the flutter speeds at high pitch angles would be sufficiently high to permit the evaluation of Mach number effects when the blades were tested in mixtures of air and Freon-12. Consequently, at low pitch angles, where the flutter speed is appreciably higher, the maximum operating speed was limited by centrifugal stresses rather than flutter.

Chordwise center-of-gravity location. The effect of chordwise center-of-gravity location on the flutter speed coefficient as a function of blade pitch angle is shown in figure 6 for blades having both NACA 23012 and NACA 23018 airfoil sections. In each case, a rearward shift in chordwise center-of-gravity location lowers the flutter speed coefficient appreciably at the lower pitch angles but has little effect on the minimum values obtained at high pitch angles in the stall region; a similar effect was also obtained for some additional model tests wherein the chordwise center-of-gravity location was moved forward as far as 22.5 percent chord. This result is apparently at variance with the results of a similar investigation of propeller blades reported in reference 2 which showed the value of the minimum flutter speed coefficient to be very much a function of the chordwise center-of-gravity location. The relation of this difference in behavior to specific differences in propeller and helicopter blade stall characteristics is not clear at present.

Airfoil section. During the investigation, it was observed that one of the blades had warped slightly, and this warping resulted in a slight upward deflection or reflection of the trailing edge. The curve of flutter speed coefficient as a function of blade pitch angle for this blade is presented with a similar curve for a blade without reflex trailing edge in figure 7. A comparison of the respective curves shows that, at pitch angles in the region of transition between classical and stall flutter, the flutter speed coefficient is considerably less for the blade having the reflex trailing edge than for the blade without the reflex trailing edge. The difference between the curves decreases, however, as the pitch angle increases and becomes nonexistent at stall. The earlier transition from classical flutter to stall flutter for the warped blade may be caused by the negative camber due to the warping. The data in reference 8 show that blades having less camber have lower flutter boundaries at pitch angles lower than the stall.

A comparison of the data presented in figures 8(a) and 8(b) shows that, at pitch angles of the order of 14°, the discrepancies between the flutter curves of the blades having different airfoil sections are small. As the pitch angle is increased, the flutter speed coefficients, for blades having similar torsional structural damping coefficients but different airfoil thickness, are considerably different. This appears to be due to the relative indifference of the minimum flutter speed

coefficient for the 18-percent-thick blades to variations in structural damping in the range of $g_{\gamma} = 0.06$.

Structural damping. The most pronounced effect of structural damping at low Mach numbers occurred at blade pitch angles in the stall region. Figure 8(a) shows that, for blades having NACA 23012 airfoil sections, the minimum flutter speed coefficient is increased appreciably by raising the torsional structural damping coefficient from $g_{\rm C}=0.049$ to 0.067. A variation in damping over a similar range $(g_{\rm C}=0.054)$ to 0.069, as shown in figure 8(b), did not appreciably affect the minimum flutter speed coefficient of the blades having NACA 23018 airfoil sections. However, when the structural damping coefficient for the NACA 23018 airfoil section was approximately tripled, a significant rise in the minimum flutter speed coefficient was obtained.

In addition to the effect of structural damping on the magnitude of the minimum flutter speed coefficient, it was observed that the flutter which occurred on the blades having high torsional structural damping coefficients was usually more violent than the flutter of the blades having low structural damping coefficients. This effect was more pronounced at the pitch-angle setting corresponding to the minimum flutter speed coefficient, and may be due to the coupled effects of nonlinearities in the structural and aerodynamic properties of the blades while operating in the flutter region.

Density .- Although the discussion presented in the previous sections was limited to data obtained at atmospheric density, data were also obtained at densities ranging from approximately 0.0012 to 0.0030 slug per cubic foot. Inasmuch as the flutter speeds obtained during the tests were found to be a function of the density, the question arose as to the most convenient method of presenting the data for different densities. An empirical expression for the classical flutter speed of a wing is given in reference 9 which shows the flutter speed to be inversely proportional to the square root of the density of the testing medium for wings having small values of the bending-to-torsion frequency ratio and values of $1/\kappa > 10$. Since the values of these parameters for the blades tested were well within the limits given in reference 9, there was reason to expect that, at low pitch angles in the region of classical flutter, the blades would flutter at constant dynamic pressure at a given pitch angle. This proved to be the case not only at low pitch angles but at high pitch angles as well. This is__ shown by the samples of data presented in figure 9 where the flutter speed coefficient is plotted as a function of the density ratio for medium and high pitch angles. Inasmuch as the straight lines through the data points show that $V_{0.8R}/b\omega_{\alpha} = C_1\sqrt{\rho_0/\rho}$, then by simple manipulation it can be shown that $\frac{1}{2}\rho V^2 = C_2$, where C_1 and C_2 are constants

which depend on the slope of the straight line and consequently are functions of the blade-pitch-angle setting. The high pitch-angle setting is near the stall angle, and the flow is probably of a non-potential nature at least during a portion of the flutter cycle.

The fact that the flutter at high pitch angles occurred at constant dynamic pressure rather than constant velocity is at variance with most of the experimental results previously obtained for wings and propellers, references 2 and 3. This difference may be due to the fact that the structural damping is much greater in the present case than for previous tests, or it might be due to aerodynamic differences associated with the different airfoil sections. The analytical and experimental investigation of reference 3 indicates that when the structural damping is very low, the minimum value of the flutter speed coefficient is essentially independent of density and the flutter will depend on the aerodynamic damping of torsional oscillations. The aerodynamic damping coefficients are shown in reference 3 to be a function of velocity and chordwise location of the torsional axis of rotation and independent of density. If, for a given axis of rotation, a region of negative damping exists, then the flutter velocity is equal to the velocity at which the aerodynamic damping becomes negative. However, if the structural damping is substantial, as is generally the case for helicopter blades, then the minimum flutter speed is shown in reference 3 to increase as the function $g_{\alpha}(r_{\alpha}^2/\kappa)$ increases. If $g_{\alpha}(r_{\alpha}^2/\kappa)$ be written in the equivalent form $g_{\alpha}(I_{\alpha}/\pi\rho b^{l_{\alpha}})$, then the minimum flutter speed is shown to increase as the density decreases, a condition which is borne out by the results of the present investigation. Whether a similar effect would be obtained by varying the mass moment of inertia I, at constant density is uncertain since no tests of this nature were made.

Discussion of the Effects of Various Parameters

on Flutter at High Tip Mach Numbers

The fact that the flutter at a given pitch angle occurred at constant dynamic pressure, as previously discussed, greatly simplifies the presentation of the data at higher Mach numbers. It effectively means that these data, taken at various densities and Mach numbers, can be represented by single curves for the different pitch-angle settings. The data presented in figure 10 for three ranges of density ratio show that the flutter boundaries obtained by plotting the flutter speed coefficient as a function of tip Mach number for various pitch-angle settings are not altered appreciably by changes in density when the flutter speed coefficient is modified by the square root of the density

ratio. This simplification is employed in subsequent discussion where the data taken at various densities are plotted in terms of the modified flutter speed coefficient $(V_{\text{O.8R}}/b\omega_{\chi})\sqrt{\rho/\rho_{\text{O}}}$.

Samples of the experimental data showing the effects of Mach number on the modified flutter speed coefficient at various blade pitch angles are shown in figures 11 and 12. These data are replotted in another form in figures 13 to 16 for use in establishing a design criterion. The operating line shown in figure 11(a) represents the line along which a given helicopter blade operates as the rotor speed is varied in a medium having a constant speed of sound. The slope of the operating line is inversely proportional to $b\omega_{\alpha}$ and directly proportional to the sound speed. Variation of any of these factors will result in an operating line having a different slope.

Blade pitch angle. The trends of flutter speed coefficient with blade pitch angle at the lower Mach numbers as shown in figures 11 and 12 are the same as those presented in figures 5 to 8. As the Mach number is increased, for each pitch-angle setting lower than the angles for minimum flutter speed coefficients, a reduction is noted in the flutter speed coefficient until some Mach number of the order of magnitude of the tip-section critical Mach number is reached. Further increases in Mach number result in a rapid rise in the flutter speed coefficient.

Although the decrease in the flutter speed coefficient is in the direction associated with compressibility effects, blade twist arising from aerodynamic forces and centrifugal body forces may be a contributing factor. The data are not sufficient to permit a generalization at this time as to the magnitude or direction of twist effects. However, some effects of Mach number on blade twist are discussed in the appendix. The tendency for a reduction in flutter speed coefficient with increasing Mach number diminishes and essentially disappears at a pitch angle approximately equal to the angle for minimum flutter speed coefficient. The magnitude of the reduction in flutter speed coefficient with increasing Mach number appears to vary somewhat from blade to blade. This is shown by a comparison of figures ll(a) and ll(b) where similar data are presented for blades number 2(r) and 3(r), respectively. primary difference between the blades is the structural damping coefficient for torsion (see table I); the damping coefficient of blade $\mathfrak{Z}(r)$ being about half that of blade 2(r).

The turnback of the flutter curves for the various pitch-angle settings represents a beneficial Mach number effect which is very similar to that exhibited by propellers (ref. 2). This beneficial effect is possibly due to a rearward shift of the center of pressure. An envelope flutter boundary can be drawn which separates the flutter regions for all

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pitch-angle settings from the flutter-free or stable regions as shown by the crosshatched curves of figures 11 and 12.

Airfoil thickness. - A comparison of figures 11(a) and 12(a) shows that the minimum flutter speed coefficient of the envelope flutter boundary for the 12-percent-thick blade is somewhat higher than that for the 18-percent-thick blade. In addition, the envelope flutter boundary for the 12-percent-thick blade turns back much more abruptly than that for the 18-percent-thick blade; however, the envelope flutter boundaries for both blades extend to a maximum Mach number of 0.73. In both cases the individual flutter boundaries, for some blade-pitch-angle settings and at Mach numbers above the Mach number at which the turnback occurs, do not tend to coincide with the respective envelope flutter boundaries but rise more steeply. This effect is noted for the 18-percent-thick blade at pitch-angle settings of 11.30, 16.10, and 20.1°, all of which are lower than the angle for minimum flutter speed coefficient. For the 12-percent-thick blade, the effect is evident at a pitch-angle setting of 21.7°, which is greater than the angle at which the minimum flutter speed coefficient occurs. In this case, the flutter boundary turns back before the envelope flutter boundary is reached. The existence of flutter boundaries which lie within the envelope flutter boundaries is a beneficial effect of Mach number over and above that exhibited by the envelope flutter boundaries themselves.

Section center-of-gravity location. - The effect of chordwise center-of-gravity location on the turnback of the flutter boundaries for different pitch-angle settings is shown for the 18-percent-thick blade by a comparison of figures 12(a) and 12(b). The data indicate that the turnback of the individual flutter boundaries for the higher pitch angles occurs at lower Mach numbers for the blade having the forward center-of-gravity location. This trend of the flutter boundaries indicates that an increase in Mach number results in a rearward shift of the center of pressure, the effect of which is apparently greater at high pitch angles. Inasmuch as the forward chordwise centerof-gravity location is near the quarter chord, (about 28.0 percent), only a slight rearward movement in center of pressure is necessary to alter appreciably the blade torsional moments, and therefore it appears logical that this effect would be more pronounced at the forward location of the center of gravity as indicated by the data. The flutter data for the 12-percent-thick blades do not indicate the same trend. It is possible that there is a smaller effect of Mach number on the location of the center of pressure for the thinner blade.

Design Criterion

A summary of the data presented herein indicates a possible design criterion that may be used to select helicopter blades which can be

operated flutter-free throughout the subsonic speed range. The nature and significance of this tentative criterion may be better understood by a discussion of the manner in which it is derived and of the blade parameters involved.

Maximum Mach number at flutter. An analysis of the data presented in table II, a portion of which is plotted in figures 11 and 12, shows that the over-all Mach number effect was such that, for the blades tested, if flutter did not occur at a tip Mach number less than about 0.73, it would not occur at any tip Mach number up to a value slightly greater than unity, the limit of the tests. The fact that the flutter boundary occurs at a tip Mach number of about 0.73 may be associated with local supercritical flow conditions and to the rearward movement of the center of pressure which is a stabilizing condition. Some evidence of this is shown by the blade-twist data presented in the appendix.

Derivation of flutter parameters .- The operating line on a flutter plot of the type shown in figures 11 and 12 is a straight radial line from the origin, the slope of which is inversely proportional to the dimensionless flutter parameter $(b\omega_{\alpha}/c)\sqrt{\rho_{\alpha}/\rho_{c}}$. A particular operating line is shown in figure 11(a). The extent to which a blade will be subjected to flutter as the rotor speed is increased depends on the slope of the operating line and the blade pitch angle. As the slope of the operating line is decreased, or conversely, as the flutter parameter $(b\omega_{\rm C}/c)\sqrt{\rho_{\rm O}/\rho}$ is increased, the ranges of pitch angles and speeds wherein flutter may be obtained gradually decrease and disappear when the operating line becomes tangent to the envelope flutter boundary. Thus the flutter parameter $(b\omega_{\rm C}/c)\sqrt{\rho_{\rm O}/\rho}$ is significant in flutter Its magnitude may be varied by varying the blade chord, blade torsional frequency, or testing medium. Generally, values of the blade chord and torsional frequency are to some extent under the control of the designer. However, it is sometimes more convenient from a research standpoint to vary the testing medium as was done in the present investigation.

In order to demonstrate more clearly the effect of the flutter parameter $(b\omega_{C}/c)\sqrt{\rho_{O}/\rho}$ on the flutter of the model blades, the data of figure ll(a) is first cross-plotted as shown in figure 13. This is accomplished by drawing a series of radial or operating lines from the origin of figure ll(a), each of which has a slope of constant $(b\omega_{C}/c)\sqrt{\rho_{O}/\rho}$. Upon intersection of a particular radial line with the flutter curve for

a given pitch-angle setting, the value of the tip Mach number is noted. The mean twist for the pitch-angle setting is then obtained from table II. Assuming a linear radial distribution of twist, the twist at 0.8R is

calculated and added algebraically to the pitch-angle setting to obtain the actual pitch angle at 0.8R at flutter. The Mach number at flutter is then plotted against the corrected pitch-angle setting $(\theta_{0.8R})_c$ for the various constant values of $(b\omega_{\chi}/c)\sqrt{\rho_0/\rho}$ as shown in figure 13. The Mach number at flutter is then replotted as shown in figure 14 as a function of the flutter parameter $(b\omega_{\chi}/c)\sqrt{\rho_0/\rho}$ for various pitch angles. The lower or envelope flutter boundary is simply a transformation of the envelope flutter boundary of figure 11(a).

Discussion of design criterion. The presentation of the data in the form of figure 14 permits a more rational evaluation of the role of some of the parameters on the envelope flutter boundary, and facilitates the discussion of the flutter region in terms of the flutter parameter $(b\omega_{\chi}/c)\sqrt{\rho_{o}/\rho}$. The figure shows that there is a maximum value of $(b\omega_{\chi}/c)\sqrt{\rho_{o}/\rho}$ above which no flutter was obtained for tests up to a tip Mach number slightly greater than unity, and this value is termed the critical value. Thus a possible criterion for stall flutter is indicated. Since, for practical applications, the sound speed is a constant, it may be possible for blades having a value of $b\omega_{\chi}$ greater than the value corresponding to this critical value to be operated flutter-free throughout the pitch-angle and Mach number range.

In order to facilitate a comparison of the results in terms of the flutter parameter for various blades having different thickness, chordwise center-of-gravity location, and structural damping, the data presented in table II were plotted and cross-plotted as discussed in the previous paragraphs to obtain envelope flutter boundaries similar to the one shown in figure 14. The resulting envelope flutter boundaries are shown in figure 15. The critical values of these envelope flutter boundaries are replotted in figure 16 as a function of structural damping. Data are also presented showing critical values of $(b\omega_{\rm C}/c)\sqrt{\rho_{\rm O}/\rho}$ for the propeller of reference 2 and the wing of reference 3.

There are no apparent effects of chordwise center-of-gravity location or thickness on the critical values of $(b\alpha_{\rm C}/c)\sqrt{\rho_{\rm O}/\rho}$. There is, however, an upward trend of the critical values as the torsional damping is reduced, and, on the basis of these results, a design criterion can be stated, namely, that helicopter blades having values of structural damping above 0.03 should be able to operate completely flutter-free if the value of the design parameter $(b\alpha_{\rm C}/c)\sqrt{\rho_{\rm O}/\rho}$ is greater than 0.3.

The critical values of $(b\omega_{\rm C}/c)\sqrt{\rho_{\rm O}/\rho}$ for the wing and propeller results as shown in figure 16 are appreciably higher than those for the helicopter blades tested, but the structural damping coefficients for the wing and propeller were much smaller than those for the helicopter blades. Structural damping appears to have considerable effect on the critical values of $(b\omega_{\rm C}/c)\sqrt{\rho_{\rm O}/\rho}$, but no conclusion can be drawn comparing the propeller and wing flutter criterion to the helicopter-blade flutter criterion since the length-to-chord ratio as well as section thickness ratio for the helicopter blades were much higher than for the wing and propeller.

It should be emphasized that the results reported herein apply specifically to the hovering case and may not be valid for conditions of forward flight.

CONCLUSIONS

The results of an experimental flutter investigation conducted in the Langley vacuum sphere flutter test apparatus to determine the effects of various parameters including Mach number on the flutter of some model helicopter rotor blades indicates the following conclusions:

- 1. Forward movement of the chordwise center-of-gravity location raised the flutter speed coefficient at low pitch angles, but had relatively little effect on the flutter speed coefficient at high pitch angles.
- 2. The minimum values of the flutter speed coefficient increased with increases in the torsional structural damping coefficient.
- 3. At a given Mach number and blade-pitch-angle setting, flutter occurred at essentially constant dynamic pressure at densities ranging from 0.0012 to 0.0030 slug per cubic foot. This was observed at all pitch angles up to the angle corresponding to minimum flutter speed coefficient.
- 4. At blade pitch angles below the stall angle, the flutter speed coefficient decreased as the Mach number was increased up to a certain value of Mach number, above which the flutter speed coefficient increased rapidly. The initial reduction disappeared at pitch angles near the stall angle.
- 5. For the blades tested, if flutter did not occur at a tip Mach number less than 0.73, it would not occur at any tip Mach number up to slightly greater than 1, the limit of the tests.

6. A tentative design criterion based on the particular tests covered is presented. This criterion implies that helicopter blades having values of the torsional structural damping coefficient greater than 0.03 and the design flutter parameter $(b\omega_0/c)\sqrt{\rho_0/\rho}$ above 0.3 should be able to operate completely flutter-free. (b = blade half-chord; ω_0 = natural first torsional frequency; c = speed of sound in testing medium; ρ_0 = standard density; and ρ = operating density.)

Langley Aeronautical Laboratory,
National Advisory Committee for Aeronautics,
Langley Field, Va., May 5, 1953.

APPENDIX

A BRIEF STUDY OF BLADE TWIST AS INFLUENCED BY BLADE PITCH

ANGLE, DYNAMIC PRESSURE, FLUTTER AND DIVERGENCE,

AND MACH NUMBER

Inasmuch as the flutter characteristics of the blades tested were found to be dependent on the blade pitch angle, it was of interest to obtain some over-all indication of the manner in which blade pitch angle was altered by blade twist. Perhaps of greater importance though is the fact that the blade twist is a good qualitative index of the chordwise location of the center of pressure, which appears to have considerable influence on the flutter characteristics of the blades. Figures 17 and 18 present some experimental measurements which show the blade twist, measured at the tip, for a 12-percent-thick blade with the chordwise center of gravity located at 37.3 percent chord. Figure 19 presents a comparison of experimental and calculated values of blade twist at a low pitch angle at rotor speeds approaching the blade divergence speed. Figures 20 and 21 show some experimental results, tabulated in table III, as to the effect of tip Mach number and divergence on blade twist.

Twist at Low Tip Mach Numbers

Some causes of blade twist .- The data points presented in figure 17 were obtained by varying the density at constant rotor speed to eliminate the effect of Mach number on twist. In addition to the aerodynamic forces and moments which produce twist, there are also body forces and moments due to the spanwise and chordwise components of the centrifugal acceleration of the blade mass particles, references 10 and 11. The spanwise components result in so-called "ribbon forces" which tend to minimize blade twist in either positive or negative directions. resulting moments are directly proportional to the blade twist and are, therefore, negligible if the twist is negligible. The chordwise components produce moments which are proportional to the sine of twice the pitch angle, the direction of which is such as to restore the pitch angle to zero. If these moments are significant for the blade in question, they should show up at the high pitch angles and would result in negative blade twist at zero density. The data presented in figure 17 for pitch angle settings of 15°, 17.5°, and 20° indicate that the twist at zero density is nearly zero (as shown by the dashed lines). Since this appears to be true for high pitch angles, it seems reasonable that the curves for low pitch angles would follow the trend indicated by the

dashed lines in showing zero twist at zero density. Thus, it is concluded for these blades that the effects of centrifugal forces on blade twist are small compared to the aerodynamic forces.

Effect of blade pitch angle. The data also show that as the pitch angle is increased from zero, the angle of twist, at a given value of dynamic pressure, also increases. This trend continues, as shown by the cross-plotted data of figure 18 until the pitch angle approaches approximately 15°, whereupon further increases in the pitch angle result in a reduction in twist. As the pitch angle approaches an angle of 25°, the blade twist is zero, indicating that the center of pressure has moved rearward and has become coincident with the center of gravity. As the pitch angle is further increased, the center of pressure apparently moves rearward of the center of gravity and the twist becomes negative.

With the exception of the blade-pitch-angle setting of 5°, the maximum value of the dynamic pressure for each blade-pitch-angle setting of the curves in figure 17 is slightly less than the dynamic pressure at which flutter occurred. No flutter was obtained at the blade-pitch-angle setting of 5°; however, the curve does show a tendency toward divergence. The limiting value of the dynamic pressure was due to the limit on the rotor speed imposed by centrifugal stresses. If flutter had occurred, it is likely that, at this relatively low pitch angle, it would have been of the classical bending-torsion type.

Theoretical prediction of twist and divergence. An attempt is made in the following paragraphs to show how the theory of references 7 and 9 may be applied to predict the divergence tendency exhibited by the blade in figure 17 at the 5° pitch-angle setting. The theory is advanced in reference 7 that the dynamic-stiffness axis may be taken as the center of gravity of the section and the divergence speed will be approximately equal to the classical flutter speed. The approximate classical flutter speed coefficient for a heavy wing with a low bending-to-torsion frequency ratio (a condition which is met by the rotor blade under consideration) was derived in reference 9 and repeated in a more convenient form in reference 7. Assuming that the effective velocity is the velocity at 0.8R, the flutter speed coefficient may be written in the modified form as follows:

$$\frac{v_{0.8R}\sqrt{\rho_0}}{b\omega_{\alpha}}\sqrt{\frac{\rho_0}{\rho_0}} = \sqrt{\frac{r_{\alpha}^2}{\kappa_0}} \frac{1/\mu}{x_{eg} - 1/\mu}$$
 (1)

where the subscript o is used to designate standard atmospheric conditions.

By substituting the appropriate values from table I for blade 3(r) into equation (l), the critical value of $(V_{0.8R}/b\omega_L)\sqrt{\rho/\rho_0}$ was determined to be 6.1 which indicates that the classical flutter or divergence speed coefficient of the blade was just slightly greater than the maximum value shown in figure 17.

According to reference 7, for small pitch angles the ratio of blade twist at successive dynamic pressures (designated by subscripts 1 and 2) may be expressed as

$$\frac{\frac{q_{1}/q_{cr}}{1 - \frac{q_{1}}{q_{cr}}}}{\frac{1 - \frac{q_{1}}{q_{cr}}}{1 - \frac{q_{2}}{q_{cr}}}} \tag{2}$$

where q_{cr} is the dynamic pressure at flutter or divergence. Inasmuch as $\left(\frac{V_{O.8R}}{b\omega_{\Omega}}\right)^2 \frac{\rho}{\rho_{o}} / \left[\left(\frac{V_{O.8R}}{b\omega_{\Omega}}\right)^2 \frac{\rho}{\rho_{o}}\right]_{cr} = q/q_{cr}$, the ratio of successive values of blade twist for corresponding values of the flutter speed coefficient becomes, after substitution of the critical values of $(V_{O.8R}/b\omega_{\Omega})^2(\rho/\rho_{o})$,

$$\left(\Delta\theta_{t}\right)_{2} = \left(\Delta\theta_{t}\right)_{1} \frac{\left[\left(\frac{V_{0.8R}}{b\omega_{\alpha}}\right)^{2} \frac{\rho}{\rho_{0}}\right]_{2} \left\{37.2 - \left[\left(\frac{V_{0.8R}}{b\omega_{\alpha}}\right)^{2} \frac{\rho}{\rho_{0}}\right]_{1}\right\}}{\left[\left(\frac{V_{0.8R}}{b\omega_{\alpha}}\right)^{2} \frac{\rho}{\rho_{0}}\right]_{1} \left\{37.2 - \left[\left(\frac{V_{0.8R}}{b\omega_{\alpha}}\right)^{2} \frac{\rho}{\rho_{0}}\right]_{2}\right\}}$$
(3)

where the constant 37.2 is the square of the critical value of the flutter speed coefficient as previously determined from equation (1) for the particular blade under consideration.

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Comparison of theory and experiment. Figure 19 presents a comparison of some theoretical and experimental values of blade twist as a function of flutter speed coefficient as the calculated divergence speed is approached. The curve of measured twist against flutter speed coefficient shown in figure 17 for a blade-pitch-angle setting of 5° is repeated along with two calculated curves, one of which is obtained from equation (3) and the other based on the assumption that the twist is directly proportional to the dynamic pressure, that is,

$$(\Delta\theta_{t})_{2} = (\Delta\theta_{t})_{1} \frac{\left[\frac{v_{0.8R}}{b\omega_{\alpha}}\right]^{2} \frac{\rho}{\rho_{0}}}{\left[\frac{v_{0.8R}}{b\omega_{\alpha}}\right]^{2} \frac{\rho}{\rho_{0}}}$$

$$(4)$$

In both instances, the initial values of blade twist and flutter speed coefficient for the calculated curves are assumed to be equal to the experimental values of $\Delta\theta_{\rm t}=0.61$ and $({\rm V_{0.8R}/b\omega_{\alpha}})\sqrt{\rho/\rho_{\rm o}}=3$. If no experimental value of twist is available, the twist may be determined from equation (3) of reference 7.

A comparison of the three curves of figure 19 shows a definite tendency of the blade toward divergence; however, the twist is not quite as great as the theory predicts, the theory being, in this case, somewhat conservative. This may be attributed partly to the increase in blade stiffness arising from centrifugal forces and, perhaps, partly to violation of the small-angle limitation of the theory.

Effect of Tip Mach Number on Blade Twist

Figures 20 and 21 show the effect of the flutter speed coefficient and blade tip Mach number on the twist of a 12-percent-thick blade operating in mediums having different speeds of sound. The chordwise center of gravity was located at 37.3 percent chord and the blade pitch angle was set at 5°. The data are presented in tabular form in table III.

Figure 20 shows the blade twist as a function of the flutter speed coefficient. The curves for the test mediums having the higher sound speeds show a tendency toward divergence at a value of $(V_{0.8R}/b\omega_{\Omega})\sqrt{\rho/\rho_{o}}$ from 3.5 to 4 whereas the curves at low sound speeds show a turnback

or reduction in twist, probably due to the effect of a rearward movement of the center of pressure as a result of the increase in Mach number. The effect of Mach number is more conveniently shown in figure 21 where the blade twist, divided by the value of the flutter speed coefficient at which it was obtained, is plotted as a function of the tip Mach number.

The curves representing data at the higher sound speeds again show a tendency toward divergence as discussed in the previous paragraph. Since this divergent tendency, as shown in figure 20, occurred at essentially constant dynamic pressure in mediums having different sound speeds, it occurs at different tip Mach numbers. As the sound speed is progressively lowered, the divergence tendency disappears and a Mach number effect becomes evident. As the Mach number approaches 0.73, a turnback in the twist curves is shown and indicates a reduction in twist with further increases in tip Mach number. The Mach number at which the turnback occurs is in agreement with the limiting Mach number of the envelope flutter boundary of figure 11(a), a fact which may indicate that the rise in the value of the flutter speed coefficient at high Mach numbers is partially due to a rearward shift of the center of pressure as evidenced by a reduction in blade pitch angle.

NACA IN 4005

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TABLE I .- CHARACTERISTIC BLADE PARAMETERS

Hub radius, 8 inches; rotor radius, 46 inches; flapping hinge radius, 2.5 inches

(a) NACA 23012 mirfoil section

Blade number	1(r)	2(f)	2(r)	3(f)	3(r)	4(r)	5(r)
Length, in	38 4	38 14	38 4	38)	38)	<u>58</u>	38 4
x _{cg} , percent chord	37.3	27.5	37.3	27.5	37.3	37.3	37.3
xEA, percent chord	26.5	25.0	- 26.5	25.0	26.5	26.5	26.5
GJ, lb-in. ²	9,980	8,260	9,210	7,800	7,900	8,210	9,980
EI, lb-in. ² ω _{h₁} , radians/sec	25,500 126	25,500 113	25,500 119	24,300 129	24,300 116	24,300 126	24,300 126
ω _{ho} , redians/sec	327	319	331	364	327	327	327
og, radians/sec	464	439	446	426	414	421	464
rα²	0.235 78.0	0.165 78.0	0.235 78.0	0.165 78.0	0.235 78.0	0.235 78.0	0.235 78.0
g _{h1}	0.126	0.105	0.110	0.134	0.093	0.170	0.135
g _{h2}	0.049	0.036	0.040		0.035	0.056	0.067
g _α · · · · · · · · · · · · · · · · · · ·	0.048	0.093	0.075	0.027	0.034	0.049	0.067
m _r , slugs	0.181	0.181	0.181	0.181	0.181	0.181	0.181
I _r , slug-ft ²	0.0055	0.0055	0.0055	0.0055	0.0055	0.0055	0.0055
σ	0.028 3.695						

(b) NACA 23018 airfoil section

	((a)	(()	=(.)	0()	2(-1)
Blade number	6(f)	6(r).	7(r) 38	8(r) 38	9(r) 38
Length, in	58 1⊾	58) J6	1 20	1 30
x _{cg} , percent chord	28.0	36.5	36.5	36.5	36.5
x _{EA} , percent chord	25.0	27.0.	27.0	27.0	27.0
GJ, lb-in. ²	18,650	20,400	14,150	16,950	16,950
EI, lb-in. ²	59,100 173	59,100 1 6 8	57,800 151.0	67,900 180	67,900 180
ω _{ho} , radians/sec	477	458	454	488	488
ω _α , radians/sec	611	616	513	576	562
rg ²	0.168	0.216	0.216	0.216	0.216
(1/κ) _ο	88.1	88.1	88.1	88.1	88.1
$g_{\mathbf{h}_1}$	0.045	0.076	0.054	0.051	0.051
8 _{h2} · · · · · · · · · · · · · · · · · · ·	0.015	0.044	0.042	0.059	0.059
g _{oz}	0.064	0.069	0.062	0.054	0.224
m _r , slugs	0.181	0.181	0.181	0.181	0.181
I _r , slug-ft ²	0.0055	0.0055	0.0055	0.0055	0.0055
σ	0.028	0.028	0.028	0.028	0.028
γ ₀	3.275	3.275	3.275	3.275	3.275

TABLE II. - TABULATION OF FLUTTER DATA

(8 _{0-8R}) _s ,	Ψ _t , ft/sec	c, ft/sec	Иt	$\sqrt{\frac{\rho}{\rho_0}}$	Vo. ar	$\frac{\mathbf{v}_{0}, 6\mathbf{R}}{\mathbf{b}\sigma_{0}}\sqrt{\frac{\rho}{\rho_{0}}}$	nr, radians/sec	Mean Δθ _t , deg	Characteristics of flutter
					naca 23012,	blade 1(r)			
2.0 5.4 4.0 4.0 5.8	574 553 548 536 535	1143 1157 1150 1150 1148	0.502 .478 .476 .466 .466	0.984 -972 -980 -980 -980	5.94 5.72 5.67 5.54 5.53	5.84 5.56 5.56 5.43 5.42	520 351 357 335 336	0.5 	Sustained Fluttered - to destruction Sustained Sustained Sustained
8.7 12.8 17.2 22.3 26.8 32.6	417 305 210 191 186 380	1152 1152 1151 1152 1154 1159	.362 .265 .182 .166 .161	.917 .977 .977 .977 .975	4.31 3.15 2.17 1.98 1.92 3.93	4.21 3.08 2.12 1.95 1.87 3.81	397 407 433 444 455 	5.1 2.2 .8 -1.8 -2.8 -3.1	Sustained Sustained Sustained Intermittent Sustained No flutter to Vt
•	-			•	MACA 25012	, blade Ω(f)			
9.1	500	1131	0.442	0.995	5-45	5.43		2.0	No flutter to V _t
11.1	477 482 516 500 500	1151 1130 1130 510 523	.422 .427 .457 .980 .956	.995 .946 .902 1.035 1.054	5.22 5.29 5.65 5.47 5.47	5.20 5.00 5.09 5.67 5.76	525 519 521 	1.3	Sustained Sustained Sustained Fo flutter to V _t To flutter to V _t
	500 407 407 413 386	547 567 585 600 600	.914 .718 .696 .688 .643	1.068 1.078 1.092 1.115 1.115	5-47 4-47 4-45 4-55 4-21	5.84 4.81 4.86 5.05 4.70	546 540 565 519		No flutter to V _t Intermittent Intermittent Intermittent Intermittent Intermittent
	402 500 444	600 620 640	.670 .807 .694	1.115 1.020 1.025	4.41 5.49 4.89	4 <u>.91</u> 5.60 5.01	528 565		Sustained No flutter to V _t *Sustained

^{*}Top of flutter region-

TABLE II. - TABULATION OF FINTER DATA - Continued

(e _{O.SR}),	Ψ _t , ft/sec	c, ft/sec	Mt	√p _o	V _{O.} 8R ЪФ _С	$\frac{v_{0.8R}}{v_{0}}\sqrt{\frac{\rho_0}{\rho_0}}$	ω _Γ , redians/sec	Mean ∆θ _t , đeg	Characteristics of flutter				
	WACA 25012, blade 2(f) - continued												
11.1	402 436 391 412 465	640 640 665 665 665	0.628 .681 .588 .620 .699	1.025 .950 1.055 1.055 1.055	4.41 4.75 4.30 4.52 5.09	4.52 4.52 4.53 4.77 5.37	503 546 509 528 578	1.3	Sustained Intermittent Sustained Sustained *Intermittent				
	417 446 407 405 453	665 665 668 705 705	.627 .671. .704 .575 .643	1.006 1.006 .940 1.080	4.58 4.89 5.14 4.42 4.94	4.60 4.91 4.83 4.78 5.34	522 565 606 512 571		Sustained *Sustained Intermittent Sustained *Sustained				
	422 413 420 482	71.0 750 750 750	•594 •551 •560 •643	-977 1.016 -977 -908	4.60 4.66 4.59 5.43	4-49 4-74 4-48 4-93	516 490 509 555	V	Intermittent Sustained Sustained Intermittent				
14.8	338 352 371 451 495	1142 1141 11340 1137 1139	.296 .307 .325 .396 .435	.990 .919 .832 .760 .696	3.69 3.82 4.05 4.94 5.45	3.65 3.53 3.57 3.75 3.77	477 489 496 521 515	.3	Sustained Sustained Sustained Sustained Sustained				
	328 362 301 352 338	494 494 495 495 497	.664 • 733 • 608 • 711 • 680	1.036 1.036 .978 .978 .892	3.61 3.99 3.29 3.84 3.70	3.74 4.14 3.22 3.76 3.30	515 565 508 558 527		Sustained *Intermittent Sustained *Intermittent Sustained				
	362 314 328 289	497 497 497 537	.728 .632 .660 .538	.892 .805 .805 1.025	3.97 3.43 3.59 3.16	3.54 2.76 2.89 3.24	565 502 521 490		*Intermittent Sustained *Sustained Sustained				

^{*}Top of flutter region.

TABLE II. - TABULATION OF FIJITER DATA - Continued

(0.8R), deg	V _t , ft/sec	c, ft/sec	М _t	$\sqrt{\frac{\rho}{\rho_0}}$	ν _{0.8R}	$\frac{A^{O*8K}}{\rho \sigma^{\alpha}} \bigwedge_{b}^{b}$	o _r , radians/sec	Mean Δθ _t , deg	Characteristics of flutter
			T.	ACA 23012,	blade 2(f)	- concluded			
14.8	372 323 381 338 362	537 537 537 537 537 537	0.695 .601 .709 .629 .674	1.025 .951 .951 .860 .860	4.07 3.53 4.17 3.70 3.95	4.17 3.29 3.88 3.18 3.40	558 502 558 512 527	0-3	*Sustained Sustained *Sustained Sustained *Sustained
	338 352 309 388 328	537 537 595 595 595 595	.629 .656 .515 .652 .551	.786 .786 1.000 1.000	3.70 3.86 3.38 4.25 3.58	2.91 3.03 3.38 4.25 3.38	502 515 489 571 502		Sustained *Sustained Sustained *Sustained Sustained
	388 336 352 372 304	595 595 595 595 660	.652 .565 .592 .625 .461	.944 .865 .785 .785 1.040	4.23 3.67 3.85 4.07 3.33	3.99 3.17 3.02 3.19 3.47			*Sustained Sustained Sustained *Sustained Sustained
	280 320 345 386	660 660 660 663	.424 .485 .527 .582	1.040 0.956 .880 .786	5.06 5.50 5.77 5.74	5.18 5.35 3.32 3.31	502 515		Sustained Sustained Sustained Sustained
19.1	239 251 263 313 345	1129 1129 1129 1129	.212 .222 .233 .278 .306	1,000 .958 .875 .795 .717	2.62 2.74 2.88 3.43 3.78	2.62 2.57 2.52 2.72 2.71	465 458 458 470 470	6	Sustained Sustained Sustained Sustained Sustained
24.6 ↓	263 301	1139 1142	.251 .264	.919	2.88 3.29	2.85 3.02	465 470	-5.1 ↓	Sustained Internittent

*Top of flutter region.

(60.8R) ₈ ,	Vt., ft/sec	c, ft/sec	Мt	V _{Po}	₹0.8R ზиξε	Ψ _{0.8R} √ ρ δα _α √ρ _ο	og, radians/sec	Mean Δθ _t , deg	Characteristics of flutter					
<u> </u>	WACA 23012, blade 2(r)													
7-2	491 500 495 500 500	11.75 11.33 11.34 498 528	0.433 .441 .437 1.004	0.985 .895 .923 .995 1.005	5.28 5.37 5.32 5.37 5.37	5.20 4.82 4.91 5.35 5.40	396 400 	4.1	Sustained No flutter to V _t Sustained No flutter to V _t No flutter to V _t					
	500 390 376 368 381	542 569 569 571 580	.923 .685 .661 .644 .657	1.030 1.040 1.040 1.110 1.928	5.37 4.19 4.04 3.95 4.09	5-50 4-36 4-20 4-38 4-21	 411 386 387		No flutter to Vt Sustained Intermittent Sustained Sustained					
•	402 500 430 500 468 498	580 585 645 648 1125 1125	.695 .855 .667 .772 .416 .443	1.028 .929 .966 .894 1.000	4.32 5.37 4.62 5.37 5.04 5.35	4.45 5.00 4.46 4.80 5.04 5.07	409 583 586		*Sustained No flutter to Vt Sustained No flutter to Vt Sustained Sustained					
11.2	362 414 458 492 318	1145 1145 1145 1147 527	.316 .362 .400 .429 .603	.979 .894 .802 .753 .971	3.89 4.45 4.92 5.29 3.42	3.81 3.98 3.95 3.98 3.32	415 428 440 446 411	1.7	Sustained Sustained Sustained Sustained Sustained					
	- 322 351 371 328 353 373 3790	533 539 542 604 607 608 608	.604 .651 .684 .543 .582 .613	1.010 .903 .783 1.000 .930 .871	5.46 5.77 5.99 3.52 3.79 4.01 4.19	3.49 3.40 3.12 3.52 3.52 3.49 3.28	411 433 452 415 427 440 452		Sustained Sustained Sustained Sustained Sustained Sustained Sustained Sustained					

^{*}Top of flutter region.



TABLE II .- TABULATION OF FLUTTER DATA - Continued

(0.88) ₈ , deg	V _t , ft/sec	c, ft/sec	Mut	<u>₽</u> / Po	Vo.&R	Vo.8R /P	or, radians/sec	Mean A ⁰ t, deg	Characteristics of flutter
				NACA 2301	2, blade 2(r) - continued			
11.2	404 347 403 403 408	608 699 709 709 709	0.664 .496 .568 .568	0.745 .991 .903 .840 .792	4-54 3-73 4-33 4-33 4-38	3.25 3.70 3.91 5.64 3.47	472 427 440 440 446	1.7	Sustained Sustained Sustained Sustained Sustained
	425 446 385 420 468	712 716 1135 1134 1133	•597 •623 •339 •370 •413	.728 .659 .984 .885 .800	4-57 4-79 4-14 4-51 5-03	3.33 3.16 4.07 3.99 4.02	776 770 727 765 779		Sustained Sustained Sustained Sustained Sustained
\	500 500 499	1133 1133 1134	.ቅት1 .ትት1 .ትት0	.690 .719 .743	5.37 5.37 5.36	3.71 3.86 3.98	459		We flutter to Yt No flutter to Yt Sustained
16.2	240 266 330 271 261	1154 1148 1150 532 545	.208 .231 .287 .510 .478	.972 .848 .693 .932 .826	2.58 2.86 3.55 2.92 2.81	2.51 2.43 2.46 2.78 2.32	409 413 423 418 414	0.3	Sustained Sustained Sustained Sustained Sustained Sustained
	51.5 546 500 250 226	556 565 566 594 595	.566 .613 .883 .421 .380	.665 .605 .558 .990	5.38 3.72 5.39 2.70 2.43	2.25 2.25 3.01 2.67 2.41	418 437 404 400		Sustained Sustained No flutter to Vt Sustained Sustained
	265 313 224 258 - 320	601 604 679 674 685	.441 .518 .330 .380 .467	.839 .693 .990 .852 .672	2.86 3.36 2.41 2.78 3.45	2.40 2.33 2.39 2.37 2.32	418 433 396 409 423		Sustained Sustained Sustained Sustained Sustained

(⁶ 0.8R) _E , deg	V _t , ft/sec	c, ft/sec	Мŧ	√ ₽	Dongs	V _{O.8R} √ρ _O	n _f , radians/sec	Mean Δθτ, deg	Characteristics of flutter
				MACA 2301	2, blade 2(r) - concluded			
21.7	268 231 255 366 466 289 482 285 292 257 286 482 298 263 298 299	1145 1150 1150 1150 1152 527 551 535 539 630 610 619 622 719 721 705	0.234 .201 .222 .314 .405 .548 .533 .548 .454 .791 .780 .479 .479 .465 .412	0.975 975 975 961 858 .71 .961 .858 .899 .894 .885 .886 .895 .885 .886 .895	2.89 2.53 2.75 3.82 5.19 3.14 7.08 5.18 5.18 5.18 5.18 5.18 5.18 5.18	2.82 2.47 2.67 3.58 2.99 4.45 2.75 2.75 2.75 2.75 2.89 4.19 2.58 2.58	428 423 423 453 470 423 428 437 419 428 427 428 428	-1.6	Sustained Sustained Sustained Sustained Sustained Sustained For flutter to Sustained
				MAC	A 23012, bl	ade 3(f)			
14.3	486 492 361 433 394	520 590 650 650 630	0.935 .834 .556 .666 .625	0.930 .974 1.024 1.024 .976	5.47 5.54 4.06 4.88 4.44	5.09 5.40 4.16 5.00 4.33	 489 533 502	1.2	No flutter to V. No flutter to V. Sustained *Sustained *Sustained
	394 364 361 377	630 740 810 1154	.625 .492 .446 .327	.976 .986 .990 .970	4.44 4.10 4.07 4.25	4.33 4.04 4.03 4.12	502 483 477 483		Sustained Sustained Sustained Sustained

TABLE II .- TABULATION OF FLUITER DATA - Continued

NACA

^{*} Top of flutter region.

TABLE II .- TABULATION OF FLUTTER DATA - Continued

(00.8R) _s , deg	V _t , ft/sec	c, ft/sec	Иt	$\sqrt{\frac{\rho}{\rho_0}}$	Vo. 8R	Vo.8R √po	ω _Γ , radians/sec	Mean Δθ _t , deg	Characteristics of flutter
		,		NACA 2301	2, blade 3(f) - concluded		,	
17.4	205 220 208 229 250 390 390 321 228	510 515 515 515 520 525 525 525 1133	0.798 ,127 ,1404 ,1415 ,1415 ,1415 ,589 ,589	0.980 .901 .901 .826 .726 .646 .688 .688	2.29 2.48 2.34 2.58 2.82 4.39 3.62 2.57	2.24 2.23 2.11 2.13 2.05 2.84 2.39 2.49 2.54	######################################	0.5	Sustained Sustained Sustained Sustained Sustained For flutter to Vt Sustained Sustained Sustained Sustained Sustained
19.2 20.0 20.2	187 168 148	1135 1135 1135	.165 .148 .130	.987 .987 .987	2.11 1.89 1.67	2.08 1.87 1.65	439 439 433	0.1 0 0	Sustained Sustained Sustained
21.5	143 202 330 222 162	1135 530 530 535 980	.126 .381 .623 .415 .165	.987 .566 .566 .536 .717	1.61 2.27 3.72 2.50 1.82	1.59 1.28 2.11 1.34 1.31	1146 152 502 1170 151	2	Sustained Sustained *Sustained Sustained Sustained
	315 198 179	535 660 750	.589 .300 .239	.536 .616 .674	3.55 2.23 2.02	1.90 1.37 1.36	489 464 458		*Sustained Sustained Sustained
25.8	156	1135	.137	.987	1.76	1.74	452	-1.2	Sustained
,	<u> </u>	·		MAC	A 23012, bl	ade 3(r)		<u> </u>	·
5.0	481.	11.35	0.424	1.000	5.58	5.58		5.0	No flutter to Vt
10.2	349 481. 481. 392	1156 560 605 630	.302 .859 .795 .622	.969 .781 .818 .842	4.05 5.58 5.58 4.54	3.92 4.36 4.57 3.82	402 427	4.5	Sustained No flutter to Vt No flutter to Vt Sustained

^{*}Top of flutter region.

TABLE II. - TABULATION OF FLUTTER DATA - Continued

(80.8R) _s , deg	V _t , ft/sec	c, ft/sec	Mt	√ <u>₽</u>	Vo.8R	Ψ _{0.8R} √ <u>ρ</u> σα ₀	or, radians/sec	Mean Δθt, đeg	Characteristics of flutter
· -	1	!	-	WACA 2301	2, blade 3(r) - concluded			•
10.2	447 380 337 334	630 670 760 835	0.708 .567 .444 .400	0.842 .855 .968 .985	5.18 4.41 3.91 3.87	4.36 3-77 3.79 3.81	458 427 402 396	4.5 	*Sustained Sustained Sustained Sustained
15.2	201 211 221 233 254	1130 510 515 515 520	.178 .413 .428 .452 .488	.992 .798 .712 .674 .628	2.33 2.45 2.56 2.70 2.94	2.31 1.96 1.82 1.82 1.85	389 408 405 408 411	2.0	Sustained Sustained Sustained Sustained Sustained
	349 441 441 257 269 237 213	520 530 530 525 525 710 830	.671 .832 .832 .490 .750 .334 .257	.628 .522 .566 .598 .598 .756	4.05 5.11 5.11 2.98 3.35 2.75 2.56	2.54 2.67 2.89 1.78 2.00 2.02 2.19			*Sustained No flutter to Vt No flutter to Vt Sustained *Sustained Sustained Sustained Sustained
17.5 20.0	156 141	11.35 11.35	.138 .124	1.000	1.81 1.63	1.81 1.63		1.4	Sustained Sustained
24.0	120 129 147	1128 505 510	.107 .256 .288	.996 .950 .646	1.39 1.50 1.70	1.38 1.42 1.10		.³	Sustained Sustained Sustained
28.0 32.0	129 201	11.35 11.35	.114 .177	1.000	1.50 2.33	1.50 2.33	****	.0 9	Sustained No flutter to V _t

^{*}Top of flutter region.



TABLE II. - TABULATION OF FLUTTER DATA - Continued

(⁶ 0.8R) _s , deg	Vt, ft/sec	c, ft/sec	Mt.	$\sqrt{\frac{\rho}{\rho_0}}$	ν _{0.8R}	$\frac{V_{0.8R}}{b\omega_{\alpha}}\sqrt{\frac{\rho}{\rho_{0}}}$	ω _Γ , radians/sec	Mean Δθt, đeg	Characteristics of flutter		
NACA 23012, blade 4(r)											
8.1 10.6 13.7 16.0 18.7 18.7 21.7 21.7	436 359 280 215 167 169 152 160 165	1149 1152 1150 1152 1151 1151 1151 1151	0.293 .336 .187 .141 .111 .112 .101 .106 .109	0.975 .973 .975 .973 .974 .974 .974	4.97 4.09 3.19 2.45 1.90 1.93 1.73 1.82 1.88	4.84 5.98 3.11 2.39 1.85 1.88 1.68 1.77	386 393 396 393 389 396 402 396 393	6.9 4.9 3.2 2.1 1.0 1.0 0	Sustained		
				NACA	23012, ъъ	ade 5(r)					
8.1 10.6 15.0 15.0 18.2 20.0 20.0 22.5 25.0	460 384 277 278 241 235 242 321	1148 1139 1141 1141 1147 1142 1142 1145 1143	0.401 .338 .243 .244 .210 .206 .204 .212	0.976 .983 .982 .982 .977 .980 .980 .978	4.76 3.97 2.87 2.88 2.50 2.43 2.41 2.50 3.32	4.65 3.90 2.82 2.83 2.44 2.38 2.45 2.45	408 423 423 417 414 420 465 414	6.5 5.8 3.1 3.1 1.3 .6	Sustained Intermittent Intermittent Sustained Sustained Sustained Intermittent Sustained No flutter to Vt		

TABLE II .- TABILATION OF FLITTER DATA - Continued

(00.8R) ₈ , deg	V _t , ft/sec	c, ft/sec	Иt	$\sqrt{\frac{p}{p_0}}$	Vo.8R book	<u>√0.8R</u> √ <u>ρ</u> α _{0χ}	ரை, radians/sec	Mean Δθτ, đeg	Characteristics of flutter
<u> </u>				1	MACA 23018, 1	olade 6(f)		<u>'</u>	
16	567 383 359 343 368	1111 555 555 544 544	0.510 .690 .647 .631 .676	1.007 .919 .919 1.003 1.003	4.45 3.01 2.82 2.69 2.89	4.49 2.77 2.59 2.70 2.90	690 655 652 625 654	1.4	Intermittent *Intermittent Intermittent Intermittent Intermittent *Intermittent
	429 362 387 453 413	606 606 660 660 734	.708 -597 -586 -686 -563	1.046 1.046 1.099 1.099	3.37 2.84 3.04 3.56 3.24	3-55 2-98 3-34 3-91 3-84	677 616 616 7 04 647		*Intermittent Intermittent Intermittent *Intermittent Intermittent Intermittent
	768 776 755 750 750	734 734 734 830 860	.599 .575 .548 .537 .544	1.183 .983 .858 .979 1.034	5.46 3.31 3.16 3.50 3.68	4.09 3.26 2.71 3.43 3.80	672 628 608 622 613		Sustained Sustained Sustained Internittent Internittent
18	418 513 516 413 381	1101 1101 1101 548 548	.379 .466 .468 .754 .695	1.019 .836 .836 1.071 1.071	3.28 4.03 4.05 3.24 -2.99	3.35 3.37 3.39 3.48 3.21	650 664 672 754 685	1.0	Sustained Sustained Sustained *Intermittent Intermittent
	340 335 373 348 389	574 574 574 625 625	.592 .584 .650 .557 .622	1.091 1.091 1.091 1.134 1.134	2.67 2.63 2.93 2.73 3.06	2.92 2.87 3.20 3.10 3.47	660 679 628 628 686		*Intermittent Intermittent *Intermittent Sustained *Sustained
\downarrow	422 349 452 388	625 625 720 720	.675 .558 .628 .539	.981 .981 1.062 1.062	3. 32 2.冲 3.55 3.05	3.25 2.69 3.77 3.24	657 628 702 647		*Intermittent Intermittent *Sustained Sustained

^{*} Top of flutter region.



TABLE II. - TABULATION OF FLUTTER DATA - Continued

(θο.8R) _s , deg	V _t , ft/sec	с, ft/sec	Mt	√ ₽ _₽	Vo.&R boox	<u>V_{0.8R}</u> / β bα ₀ ,	a _f , radians/sec	Meen Δθτ, deg	Characteristics of flutter			
	WACA 23018, blade 6(f) - continued											
18	362 407 424 545 395	780 780 780 490 840	0.464 ,522 ,544 1.111 ,470	1.145 .988 .988 1.056 1.072	2.84 3.20 3.33 4.28 3.10	3.26 3.16 3.29 4.53 3.33	628 655 660 663	1.0	Sustained Intermittent *Sustained *Mo flutter to Vt Intermittent			
	403 410 495 471	840 840 840 840	.480 .488 .589 .561	1.072 1.001 1.001 1.001	3.17 3.22 3.89 3.70	3.40 3.23 3.90 3.71	628 637 680 684		Sustained Sustained *Intermittent *Bustained			
20	336 425 520 504 282	1120 1120 1120 1120 1120 560	.300 .379 .464 .450 .504	1.003 -751 -751 -751 1.075	2.64 5.34 4.08 3.96 2.22	2.65 2.51 3.07 2.97 2.38	612 660 672 652 605	0.4	Sustained Intermittent Intermittent Sustained Sustained			
	275 418 286 296 322	560 1120 560 664 664	.491 .373 .511 .446 .485	1.075 .751 1.075 1.158 .994	2.16 3.28 2.25 2.33 2.53	2.32 2.46 2.42 2.69 2.52	602 65¼ 602 595 622		*Sustained Sustained *Sustained Sustained Intermittent			
	306 310 301 306 452	664 664 664 735 735	.461 .467 .453 .416 .615	.994 .994 .994 1.085	2.40 2.44 2.36 2.40 3.55	2.39 2.42 2.35 2.61 3.85	597 612 612 597 698		Sustained Intermittent Intermittent Sustained *Sustained			
	338 345 311 338	735 735 830 830	.460 .469 .375 .407	.955 .955 1.069 .953	2.65 2.71 2.14 2.66	2.54 2.59 2.61 2.53	613 609 602 618		Intermittent *Intermittent Sustained Sustained			

^{*}Top of flutter region.

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(80.8R) _g ,	V _t , ft/sec	c, ft/sec	Мt	<u>√₽</u> .	Vo.8R → Del(x	<u>Vo.8R</u> √ <u>p</u> boo _s √p _o	og, radians/sec	Mean Δθt, deg	Characteristics of flutter
		 	H	ACA 23018,	blade 6(f)	- continued			
2 0 →	404 563 563	850 503 500	0.487 1.120 1.130	0.953 .869 1.054	3.17 4.42 4.42	3.93 3.84 4.67	625 	9.4	*Sustained No flutter to Vt No flutter to Vt
22	267 348 360 261 282	11.33 11.29 11.29 564 564	.236 .308 .319 .463 .500	.990 .767 .767 1.073	2.10 2.75 2.85 2.05 2.22	2.08 2.10 2.17 2.20 2.38	593 620 606 583 590	-1	Sustained Internitient Sustained Sustained *Sustained
	235 270 362 261 281	670 670 670 800 800	.351 .403 .540 .328 .353	1.162 1.019 1.019 1.038 .960	1.85 2.12 2.84 2.05 2.21	2.15 2.16 2.90 2.13 2.12	593 595 628 • 600 598		Sustained Sustained *Sustained Sustained Sustained
	385 563 563	800 494 490	.484 1.140 1.150	.960 .847 1.020	3.03 4.42 4.42	2.91 3.76 4.52	6 <u>2</u> 8	\	*Sustained No flutter to Vt No flutter to Vt
2 1	243 299 3 04 241 233	1117 1118 1118 1118 572 572	.218 .267 .272 .421 .407	1.007 .850 .850 1.073	1.91 2.35 2.39 1.89 1.85	1.92 2.00 2.03 2.03 1.97	586 616 604 570 576	0	Sustained Intermittent Sustained Sustained Sustained
\	253 249 234 245 253 263 296	580 580 583 583 690 690	.456 .429 .401 .420 .338 .381 .429	.979 .979 .979 .979 .979 1.085 .944	1.99 1.96 1.84 1.95 1.85 2.07 2.33	1.95 1.92 1.80 1.89 1.99 2.20	570 576 576 576 576 583 586		Sustained Sustained Sustained *Sustained Sustained Sustained *Sustained

^{*}Top of flutter region.

TABLE II .- TABLEATION OF FLUTTER DATA - Continued

(a _{0.8g}) _g ,	V _t , ft/sec	c, ft/sec	Mt	√ <u>₽</u>	₹ 0.8R Ъщ ₂	Ψ _{0.8R} /ρ α _α /ρο	mp, radians/sec	Mean Δθt, deg	Cherecteristics of flutter				
	NACA 23018, blade 6(f) - continued												
5)4	251 252 377 560 560	785 783 783 500 500	0.295 .322 .481 1.120 1.120	1.031 .968 .968 .906 1.015	1.82 1.98 2.96 4.40 4.40	1.87 1.92 2.87 3.99 4.47	585 575 614	°	Sustained Sustained *Sustained No flutter to Vt				
56	227	1130	-201	-994	1.78	1.77	581.	0	Sustained				
27	197 246 230 259 221 218 345 222	1120 1120 580 580 668 668	.176 .220 .397 .447 .331	1.007 1.007 .992 .996 .996 .996	1.58 1.93 1.81 2.03 1.件 1.71 2.71 1.件 1.66	1.59 1.95 1.79 2.02 1.73 1.71 2.70 1.74 1.67	608 598 576 572 588 582 616	1	Sustained Sustained Sustained *Sustained Sustained Sustained *Sustained				
	211 222 561.	754 824 824 500	.517 .294 .256 .269 1.122	1.007 1.007 1.011	1.66 1.75 4.41	1.67 1.76 4.46	582 616 568 572 565		Intermittent Sustained No flutter to Vt				
28	225	1129	.199	•996	1.77	1.76	588	1	Sustained				
30	441 441 441 259 258	502 500 584 1129 644	.878 .882 .755 .229 .401	.944 1.015 1.023 .996 1.056	3.47 3.47 3.47 2.04 2.03	3.27 3.51 3.54 2.03 2.14	588 602	5	No flutter to Vt No flutter to Vt No flutter to Vt Sustained Sustained				
	259 250 262 287	644 644 723 723	.402 .388 .362 .397	1.005 1.005 1.013 1.013	2.04 1.97 2.06 2.26	2.05 1.97 2.09 2.29	608 608 600 593		Intermittent *Intermittent Intermittent Sustained				

^{*}Top of flutter region.

TABLE II .- TABULATION OF FLUTTER DATA - Continued

(\theta_0.8R)_g, deg	V _t , ft/sec	c, ft/sec	Mt	√ <u>₽</u> √₽,	Vo.8R	<u>V_O.8aR</u> √ ρ ν _O	σ _f , radians/sec	Meen A6t, deg	Characteristics of flutter
		·	N	ACA 23018,	blade 6(f)	- concluded			
30	305 253 291 320 278	723 763 765 765 842	0.422 .322 .371 .468 .330	1.013 1.009 1.009 1.009 .994	2.40 1.99 2.29 2.52 2.19	2.43 2.01 2.31 2.54 2.17	603 614 606 603 606	-0.5	*Sustained Internationat Sustained *Bustained Sustained
				MAGA	23018, blad	e 6(r)	·		
11.3	525 547 600 541 578 561 407 419 561 425 445	1126 1128 1129 1131 530 580 625 625 625 625 625 626	0.466 .485 .531 .478 1.091 .967 .670 .898 .646	0.990 .924 .872 .944 1.013 1.058 1.083 1.040 1.068	4.09 4.27 4.67 4.21 4.50 4.37 5.17 5.26 4.37 3.31	4.05 3.93 4.07 3.98 4.56 4.62 3.43 3.54 4.54 3.53 3.70 3.77	559 571 581 565 578 590 572 600	3.80	Sustained Sustained Sustained Sustained No flutter to Vt No flutter to Vt Sustained *Sustained To flutter to Vt Sustained *Sustained *Bustained To flutter to Vt
	445 482 441 470 452 470 458 463 445	68 68 68 68 68 68 68 68 68 68 68 68 68 6	.750 .644 .686 .660 .686 .667 .676 .627	1.005 1.031 1.031 .996 .957 .957	3.75 3.44 3.66 3.52 3.66 3.57 3.61 3.47	3.77 3.54 3.77 3.51 3.65 3.41 3.45 3.45	594 612 597 615 606 616 576		*Sustained *Sustained Sustained *Sustained *Sustained Sustained *Sustained *Sustained *Sustained Sustained

^{*}Top of flutter region.

TABLE II .- TABULATION OF FLUTTER DATA - Continued

(0.8R), deg	V _t , ft/sec	c, ft/sec	Mt	$\sqrt{\frac{\rho}{\rho_0}}$	Vo.8R	<u>Vo.8</u> R √ρ bαα γρο	or, radians/sec	Mean A0t, deg	Characteristics of flutter
	· ·		,	ACA 23018,	blade 6(r)	- continued			
11.3	490 459 466 495	710 714 714 718 718	0.690 .643 .679 .649 .671	0.996 .951 .951 .912	3.82 3.57 3.78 3.63 3.75	3.80 3.40 3.60 3.31 3.42	619 597 622 597 609	3.80	*Sustained Sustained *Sustained Sustained Sustained *Sustained
	463 482 452 499 474	720 720 725 725 725	.643 .669 .623 .688 .654	.875 .875 .875 .875 .805	3.61 3.75 3.52 3.89 3.69	3.15 3.28 3.18 3.40 2.97	597 587 628 590		Sustained *Sustained Sustained *Sustained Sustained
	448 466 494 499 510 516	785 785 785 785 910 910	.571 .594 .629 .636 .560	1.085 1.013 .901 .789 .996 .942	5.49 5.63 5.85 5.89 3.97 4.02	5.78 5.68 5.47 5.07 3.96 3.79	565 5775 594 597 584 584		Sustained Sustained Sustained Sustained Sustained Gustained
16.1	362 369 405 438 467	1097 1098 1098 1098 1098	.330 .336 .369 .399 .425	1.027 .975 .894 .825	2.82 2.87 3.15 3.41 3.64	2.90 2.82 2.82 2.82 2.72	575 578 590 594 600	2.0	Sustained Sustained Sustained Sustained Sustained
	285 351 287 294 302	\$\$\$\$\$\$ \$444	.588 .724 .592 .606 .623	1.139 1.139 1.066 1.066 1.003	2.22 2.73 3.01 2.29 2.35	2.53 3.11 2.39 2.44 2.36	597 628 597 612 609		Sustained *Sustained Sustained *Sustained Thtermittent

^{*}Top of flutter region.

TABLE II .- TABULATION OF FLUTTER DATA - Continued

(60.8R) _s , deg	V _t , ft/sec	c, ft/sec	и _t	$\sqrt{\frac{p}{p_0}}$	<u>√0.8R</u> bæ _x	Vo.8R √p baby √po	ω _r , radians/sec	Mean Ag _t , deg	Characteristics of flutter
	L. =- 11·1			MACA 2301	8, blade 6(r) - Continued			
16.1	562 353 429 351 380	1487 620 620 628 628	1.154 .569 .692 .559 .605	0.935 1.037 1.037 960 .960	4.38 2.75 3.34 2.73 2.96	4.09 2.85 3.46 2.63 2.84	609 653 616 616	2.0	No flutter to V _t Sustained *Sustained Sustained *Sustained *Sustained Intermittent
	376 552 364 362 386	632 635 750 760 762	.595 .869 .485 .476 .507	.911 .865 .995 .939 .884	2.93 4.30 2.83 2.82 3.00	2.67 3.72 2.82 2.65 2.66	590 565 565 584		No flutter to Vt Sustained Sustained Sustained
	483 408 487 485 495	762 762 762 762 762	.654 .555 .639 .558 .650	.884 .822 .770	3.76 3.18 3.79 3.31 3.85	3.33 2.61 3.12 2-55 2.96	628 584 622 587 628		Sustained Sustained *Sustained Sustained *Sustained
20.1	256 268 294 321 376	1098 1096 1096 1097 1097	.233 .245 .268 .293 .343	1.029 .979 .899 .844 .775	1.99 2.09 2.29 2.50 2.95	2.05 2.04 2.05 2.11 2.27	597 603 603 603 603	0.7	Sustained Sustained Sustained Sustained Sustained
	386 227 256 236 311	1098 1495 1495 1495 1495	.752 .459 .517 .477 .628	721 1.025 943 1.051 1.051	3.00 1.77 1.99 1.84 2.42	2.17 1.81 1.88 1.93 2.54	603 597 603 597 622		Sustained Sustained Intersittent Sustained Sustained
	236 294 258	495 495 495	.\77 .593 .520	.998 .998 .963	1.84 2.29 2.01	1.83 2.28 1.93	584 606 597		Sustained Sustained Sustained

*Top of flutter region.

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TABLE II .- TABULATION OF FLUTTER DATA - Continued

(Go.8R)s'	Vt, ft/sec	c, ft/sec	Мt	$\sqrt{\frac{\rho}{\rho_0}}$	Vo.8R	<u>₹ი.8R</u> <u>/ρ</u> Ծա _{0α} / ρο	ω _Γ , radians/sec	Mean Δθι, deg	Characteristics of flutter
				NACA 2301	8, blade 6(r) - continued			
20.1	272 563 284 339 295	495 495 615 615 615	0.550 1.137 .461 .551 .480	0.963 .905 .938 .938 .878	2.12 4.38 2.21 2.64 2.30	2.04 3.97 2.07 2.48 2.02	612 609 615 615	0.7	*Sustained No flutter to V _t Sustained *Sustained Intermittent
	557 232 445 249 436	630 627 627 627 627	.884 .369 .710 .397 .695	.833 1.074 1.074 1.018 1.018	4.34 1.81 3.46 1.94 3.39	5.61 1.94 3.72 1.98 3.45	597 676 584 597		No flutter to V _t Sustained *Sustained Sustained *Sustained
	261 425 281, 397 285	627 627 627 627 627	.416 .678 .448 .633 .455	.970 .970 .935 .935 .894	2.03 3.31 2.19 3.09 2.22	1.98 3.21 2.04 2.89 1.99	581. 641. 597 625 597		Sustained *Sustained Sustained *Sustained Sustained
	342 292 330 297 312	627 627 627 627 627 627	.546 .466 .526 .474 .498	.894 .882 .882 .863 .863	2.66 2.27 2.57 2.31 2.43	2.38 2.01 2.27 2.00 2.09	609 597 603 590 610		*Sustained Sustained *Sustained Sustained *Sustained
	289 268 281 301 336	627 770 770 770 770	.461 .348 .365 .391 .436	.842 .978 .943 .891 .807	2.25 2.09 2.19 2.35 2.62	1.90 2.05 2.06 2.09 2.11	603 581 590 590 603		Intermittent Sustained Sustained Sustained Sustained
	565 432 482	770 1106 1106	. 734 . 391 . 436	.750 .672 .651	4.40 3.37 3.76	3.30 2.26 2.45	581 597		No flutter to V _t Sustained Sustained

^{*}Top of flutter region.

TABLE II .- TABULATION OF FLUTTER DATA - Continued

⁽⁶ 0.8R) ₈ ′ deg	V _t , ft/sec	c, ft/sec	Мt	√ <u>₽</u> ₽ ₀	V _{0.8R} ba _{0x}	Ψ _{O.8R} √ <u>ρ</u> του _α √ρο	or, radians/sec	Mean Δθτ, deg	Characteristics of flutter
				NACA 2301	8, blade 6(r) - continued			
23.4	252 268 273 295	1112 1112 1112	0.227 .241 .246 .265	1.013 .9Կ .689 .831	1.96 2.09 2.13 2.30	1.99 1.97 1.89 1.91	572 565 572 578	0	Sustained Sustained Sustained Sustained
	359 429 579 305 223	1112 1112 1115 497 497	.323 .386 .519 .614 .449	.752 .695 .645 .999	2.80 3.34 4.51 2.38 1.74	2.10 2.33 2.91 2.38 1.73	578 587 612 597 565		Sustained Sustained Sustained *Intermittent Intermittent
	341 220 327 263 336	497 497 497 497 497	.686 .443 .658 .529 .676	1.026 1.026 1.056 1.056 1.087	2.66 1.71 2.55 2.05 2.62	2.73 1.76 2.69 2.16 2.85	609 572 590 603 609		*Intermittent Intermittent *Intermittent Intermittent Intermittent *Intermittent
	235 214 341 254 351	497 497 497 560 560	.473 .431 .686 .454 .627	1.087 1.116 1.116 .996	1.83 1.67 2.65 1.98 2.73	1.99 1.86 2.96 1.97 2.72	585 581 622 559 609		Intermittent Intermittent *Intermittent Sustained *Sustained
	254 349 251 341 563 337 268	562 562 563 563 565 570 570	.452 .621 .446 .606 .997 .591 .470	.954 .954 .913 .913 .847 .876	1.98 2.72 1.96 2.66 4.38 2.63 2.09	1.89 2.59 1.78 2.43 5.71 2.30 1.83	559 597 559 590 590 562	↓ ↓	Sustained *Sustained Sustained *Sustained *Sustained No flutter to V _t *Sustained Sustained

^{*}Top of flutter region.



TABLE II.- TABULATION OF FLUTTER DATA - Continued

(θο.8R) _s , deg	V _t , ft/sec	c, ft/sec	Мt	\ <u>P</u>	V _{O.8R} buox	<u>ν_{0.8R}</u> <u>ρ</u> του _α <u>νρο</u>	ധ _ך , radians/sec	Mean Δθτ, deg	Characteristics of flutter
			NA	CA 2301	.8, blad	e 6(r) - co	ncluded		
23.4	254 423 271 397 565 298 396 255 281 486 313 389 386 310 565	660 660 660 660 660 660 763 763 763 763 763 763 763	0.385 .641 .411 .602 .856 .452 .600 .334 .368 .637 .410 .506 .406 .741	0.933 .933 .881 .821 .850 .922 .866 .866 .807 .791 .791 .771	1.98 3.30 2.11 3.09 4.40 2.32 3.09 1.99 2.19 3.79 2.44 3.03 3.01 2.42 4.40	1.85 3.07 1.86 2.73 3.61 1.97 2.62 1.83 1.90 3.27 1.97 2.44 2.35 1.91 3.39	559 635 565 603 572 597 553 553 635 573 581 565 	0	Sustained *Sustained Sustained Sustained No flutter to Vt Sustained Sustained Sustained Sustained Sustained Sustained Intermittent

^{*}Top of flutter region.

TABLE II - TABULATION OF FLUTTER DATA - Concluded

(θ0.8R) _s , deg	V _t , ft/sec	c, ft/sec	Иt	√ P Po	Vo.8R bub	<u>V_O.8R</u> √ ρ bαα √ρ _ο	or, radians/sec	Mean ∆9t, deg	Characteristics of flutter
				MAC	A 23018, bl	ade 7(r)			
11.0 13.0 15.0 17.0 19.3 22.3	508 402 353 283 231 214 241	1130 1129 1130 1131 1132 1132 1132	0.450 .356 .312 .250 .204 .189 .214	0.997 .997 .995 .995 .993 .993	4.74 3.75 3.30 2.64 2.16 2.00 2.25	4.72 3.74 3.28 2.63 2.14 1.99 2.24	538 524 523 514 516 502 502	2.3 2.1 1.6 1.3 .5	Intermittent Sustained Sustained Sustained Sustained Sustained Sustained Sustained
			•	1AM	1 23018, ъ1	ade 8(r)			
13.0 15.0 17.0 19.3 22.0 25.8	1444 365 308 252 250 275	1119 1127 1126 1122 1122 1122	0.397 .324 .274 .225 .223 .245	1.005 .997 .998 1.002 1.002	3.70 3.04 2.57 2.10 2.08 2.29	3.72 3.03 2.56 2.11 2.09 2.30	579 565 570 576 566 593	3.2 2.3 1.5 .8 .2	Sustained Sustained Sustained Sustained Sustained Thtermittent
				MAC	А 23018, ъ1	ade 9(r)			
13.0 15.0 17.0 19.3 22.0 25.8	452 421 351 301 276 337	1119 1127 1126 1122 1122 1122	0.405 .373 .312 .268 .246	1.005 .997 .998 1.002 1.002	3.86 3.60 3.00 2.57 2.36 2.88	5.88 5.59 2.99 2.58 2.37 2.89	565 575 557 542 534 530	3.2 2.3 1.5 .8 .2	Sustained Sustained Sustained Sustained Sustained Sustained Sustained

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TABLE III. - EFFECT OF MACH NUMBER AND DIVERGENCE ON BLADE TWIST NACA 23012 blade 4(r); $(\theta_{0.8R})_s = 5^\circ$; atmospheric density

c	Vt	Мቲ	V _{0.8R} √ ρ bω _α	Δθţ	$\frac{\frac{\Delta\theta_{t}}{v_{0.8R}}\sqrt{\frac{\rho}{\rho_{0}}}}{v_{0}}$
500	160 240 320 360 400 440 480	0.32 .48 .64 .72 .80 .88	1.83 2.74 3.65 4.11 4.57 5.03 5.49	0.5 1.3 3.1 4.1 4.4 4.0	0.27 .47 .85 1.00 .96 .88
565	160	.28	1.83	1.1	.60
	240	.43	2.74	1.9	.69
	320	.57	3.65	3.1	.85
	360	.64	4.11	4.3	1.05
	400	.71	4.57	6.1	1.34
602	160	.27	1.83	1.0	.55
	240	.40	2.74	1.8	.66
	320	.53	3.65	2.8	.77
	360	.60	4.11	3.3	.80
	400	.67	4.57	5.6	1.23
	7480	.67	84.01	4.0	al.00
	7740	•73	5.03	6.2	1.23
	740	•73	84.41	4.9	al.11
	7400	•80	84.80	4.9	al.02
715	160 240 320 400 420	.22 .34 .45 .56	1.83 2.74 3.65 4.57 4.80	.7 1.2 1.9 5.2 7.0	.38 .44 .52 1.14 1.46
1120	160	. 14	1.83	.8	.44
	320	. 28	3.65	1.9	.52
	400	. 36	4.57	5.2	1.14
	480	. 43	5.49	9.5	1.73

^aDensity reduced to 0.77 atmosphere.

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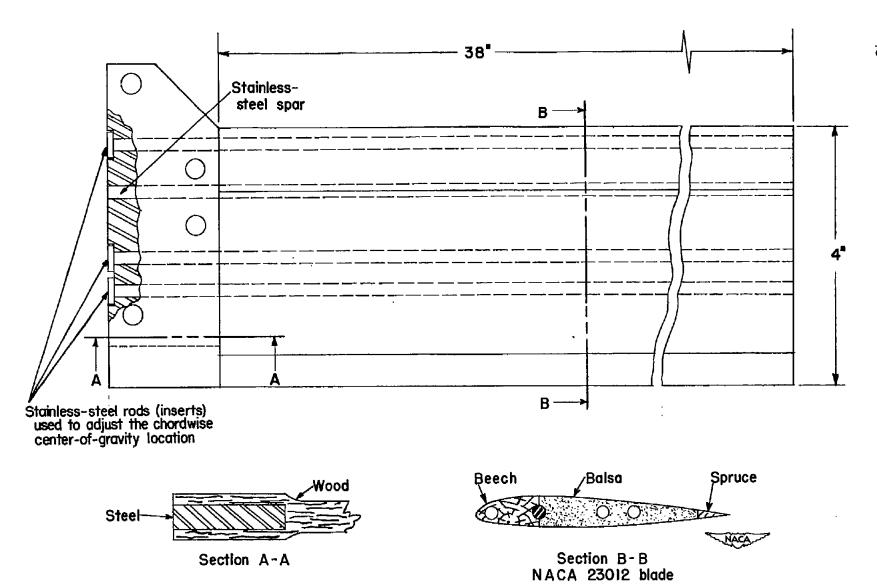


Figure 1.- Schematic drawing of blade showing method of varying chordwise center-of-gravity location.

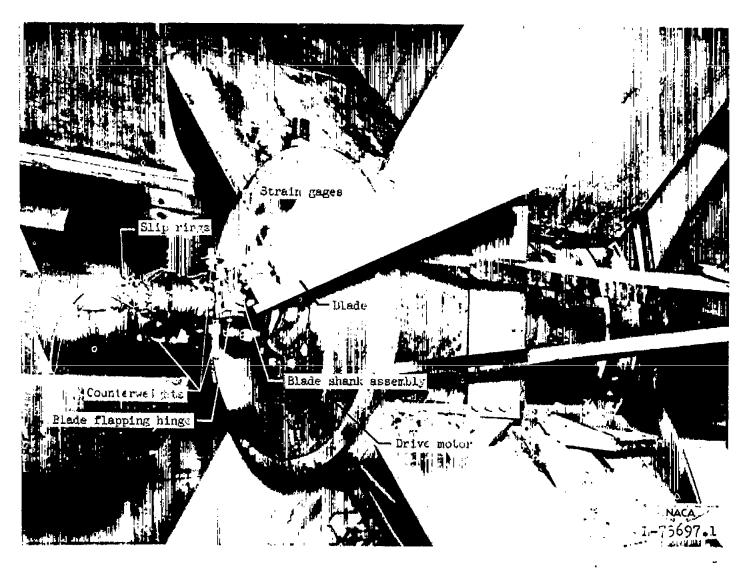


Figure 2.- Rotor-blade assembly as viewed with the hub mounted on the motor shaft inside the vacuum sphere.

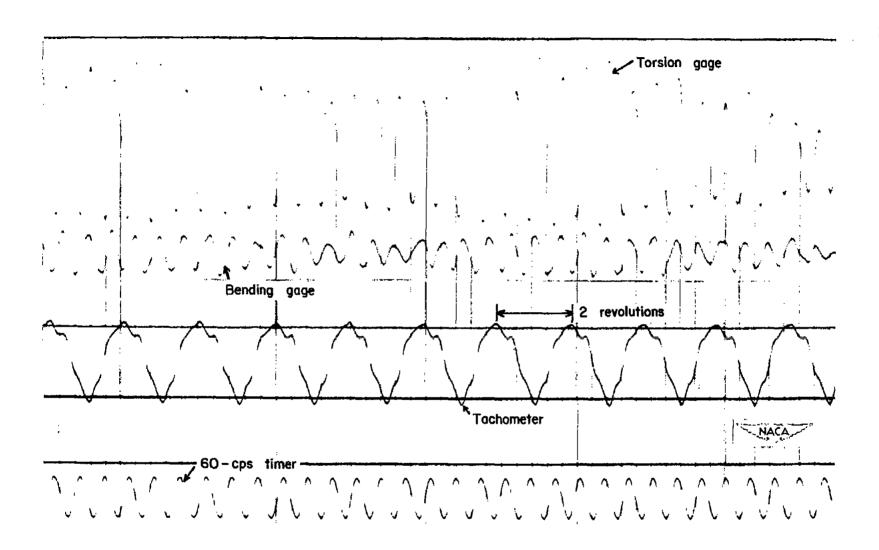


Figure 3.- Sample flutter record.

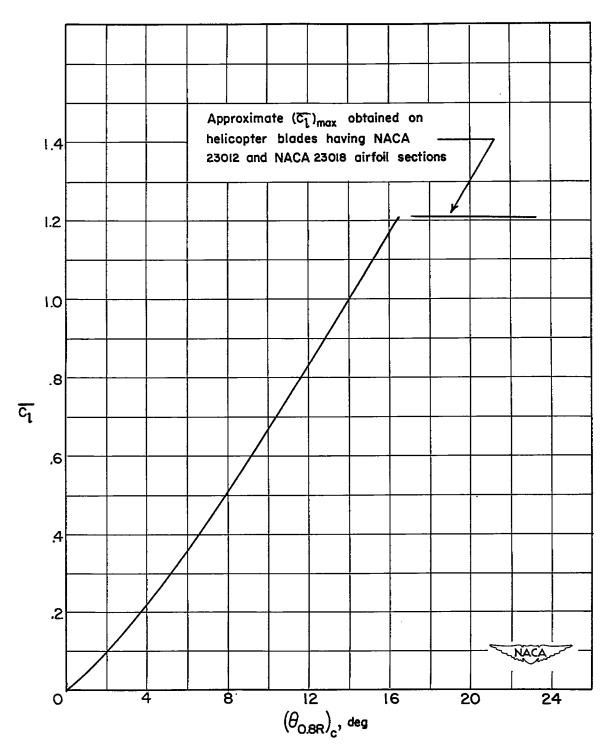


Figure 4.- Mean section lift coefficient for the NACA 23012 and 23018 blades as a function of the blade pitch angle. (The lift coefficient is calculated by Glauert's method, ref. 6, based on a blade element located at 0.8R.) $\sigma=0.028$.

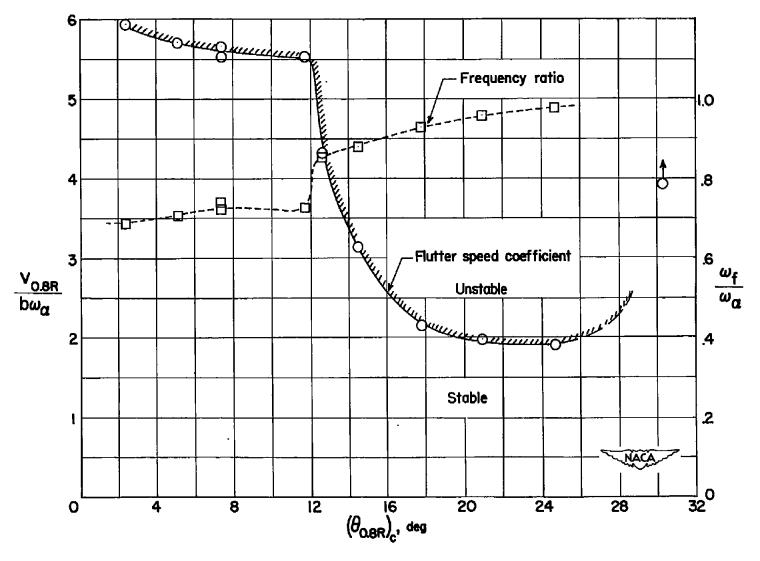


Figure 5.- The variation of flutter speed coefficient and flutter frequency ratio with blade pitch angle for blade l(r) at atmospheric density. $M_{\rm t} < 0.51$.

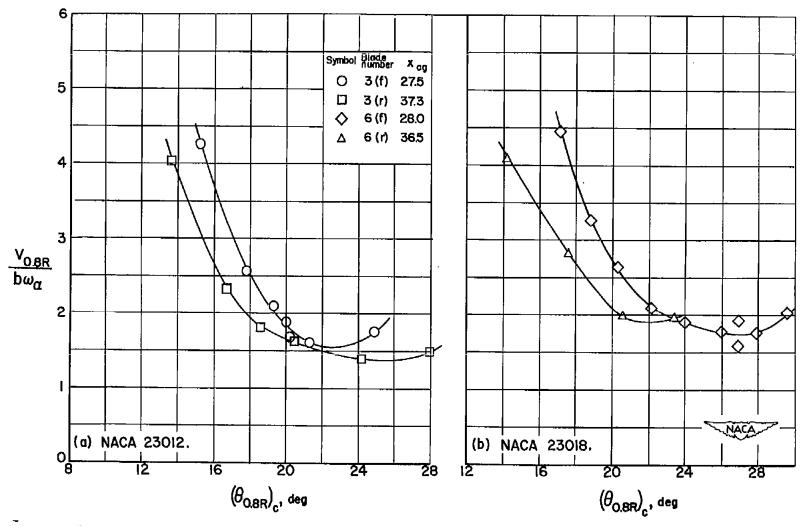


Figure 6.- The effect of chordwise center-of-gravity location on the flutter speed coefficient as a function of blade pitch angle at atmospheric density for blades having both NACA 23012 and NACA 23018 airfoil sections. $M_{\rm t} < 0.51$.

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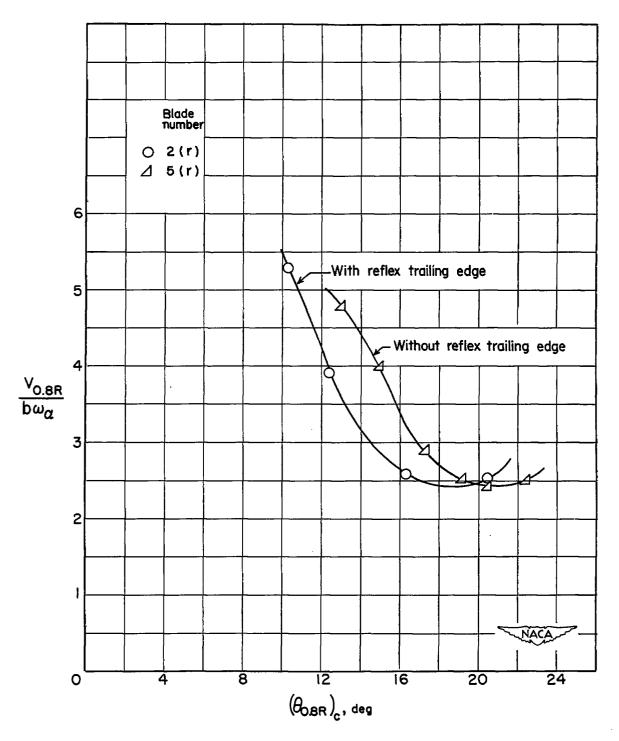


Figure 7.- The effect of blade airfoil shape on the flutter speed coefficient as a function of blade pitch angle at atmospheric densities. Mt <0.144 .

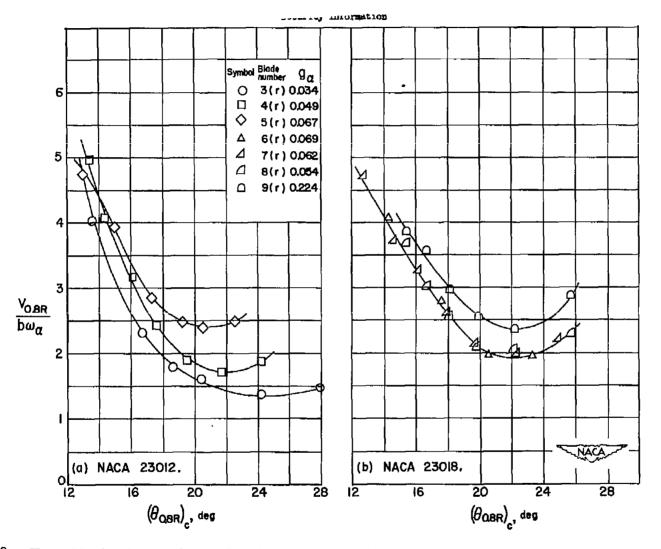


Figure 8.- The effect of structural damping on the flutter speed coefficient as a function of blade pitch angle at atmospheric density for blades having both NACA 23012 and NACA 23018 airfoil sections. $M_{\rm t} < 0.43$.

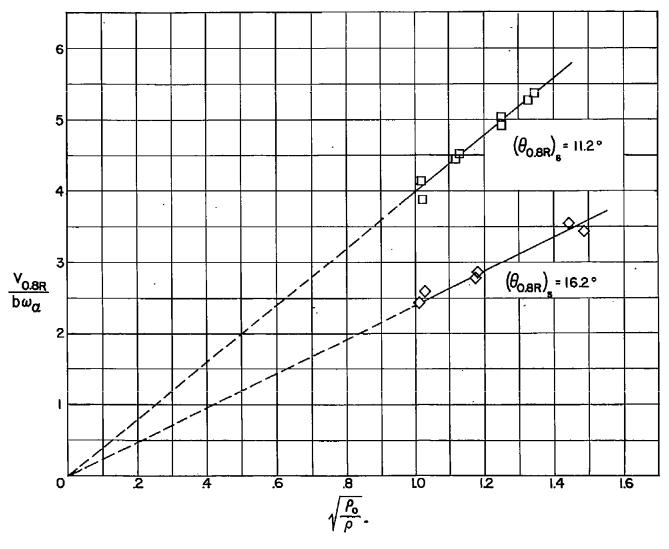


Figure 9.- The effect of density on the flutter speed coefficient at medium and high pitch angles for blade number 2(r). $M_t < 0.42$.

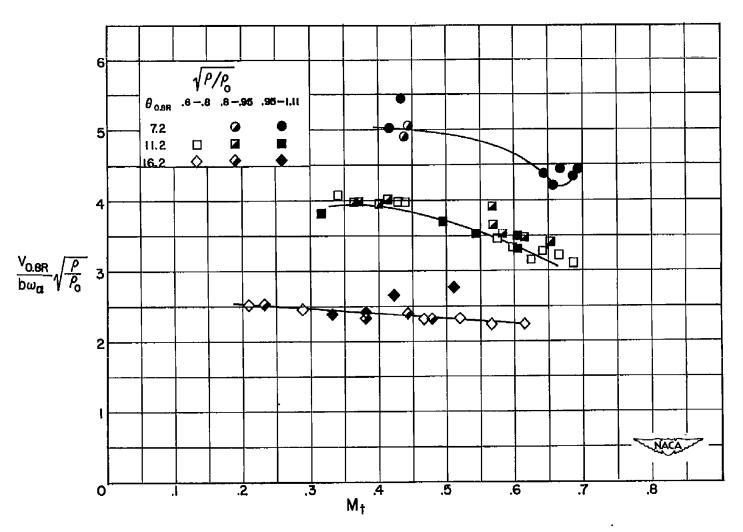
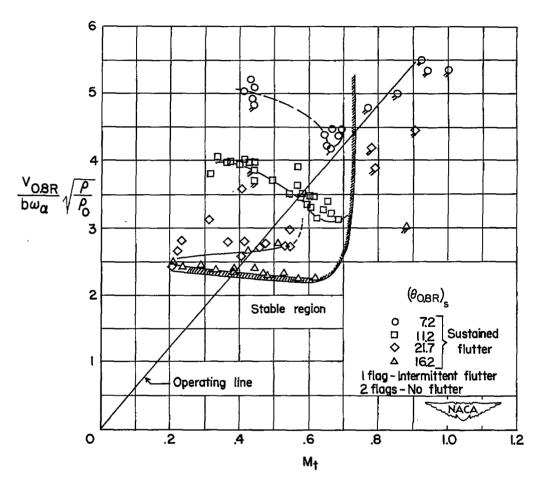
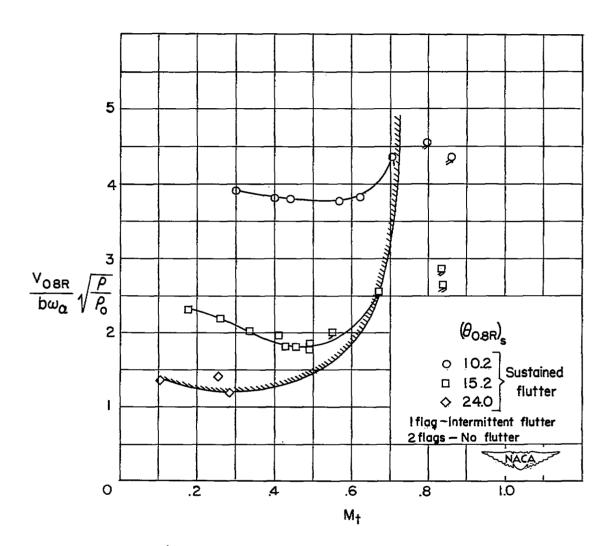


Figure 10.- The modified flutter speed coefficient as a function of tip Mach number at various pitch angles. (Data are presented for different density ratios to show that the flutter boundaries are not altered by changes in density when the flutter speed coefficient is modified by the square root of the density ratio.)



(a) Blade number 2(r); $g_{\alpha} = 0.075$.

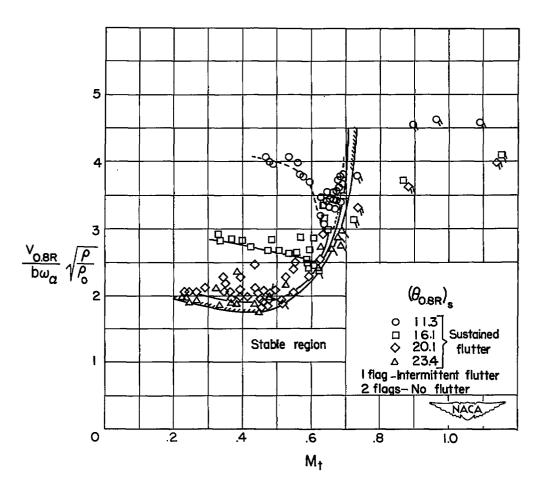
Figure 11.- The effect of tip Mach number on the modified flutter speed coefficient at various pitch-angle settings for two blades having NACA 23012 airfoil sections.



(b) Blade number 3(r); $g_{\alpha} = 0.034$.

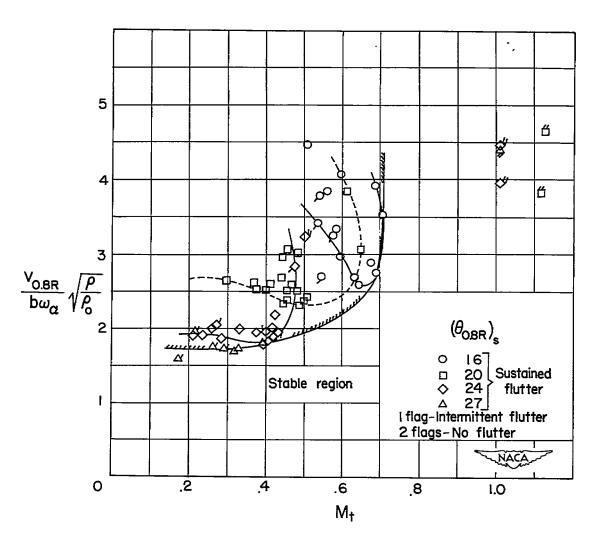
Figure 11.- Concluded.

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(a) Blade number 6(r); $g_{\alpha} = 0.069$.

Figure 12.- The effect of tip Mach number on the modified flutter speed coefficient at various pitch-angle settings for a blade having an NACA 23018 airfoil section at different chordwise center-of-gravity locations.



(b) Blade number 6(f); $g_{\alpha} = 0.064$.

Figure 12.- Concluded.

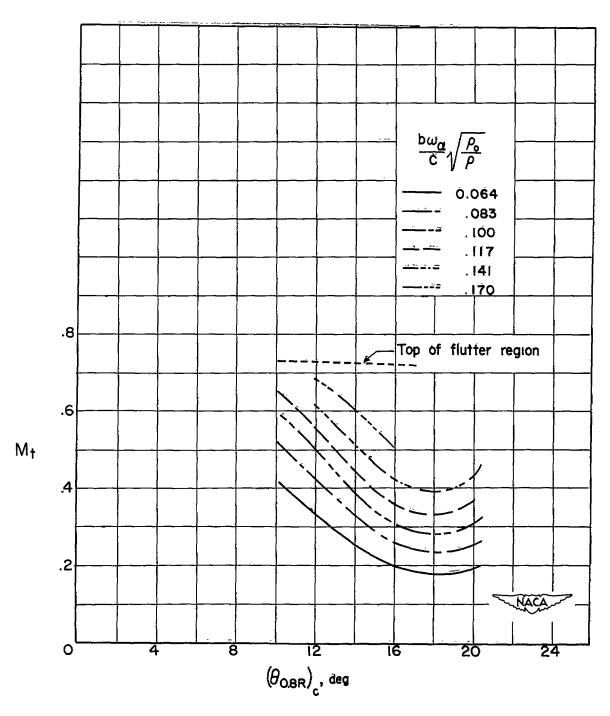


Figure 13.- The effect of blade pitch angle (corrected for twist) on the tip Mach number at flutter for various values of the dimensionless flutter parameter $\frac{b\omega_0}{\bar{c}}\sqrt{\frac{\bar{\rho}_0}{\rho}}$ for blade 2(r).

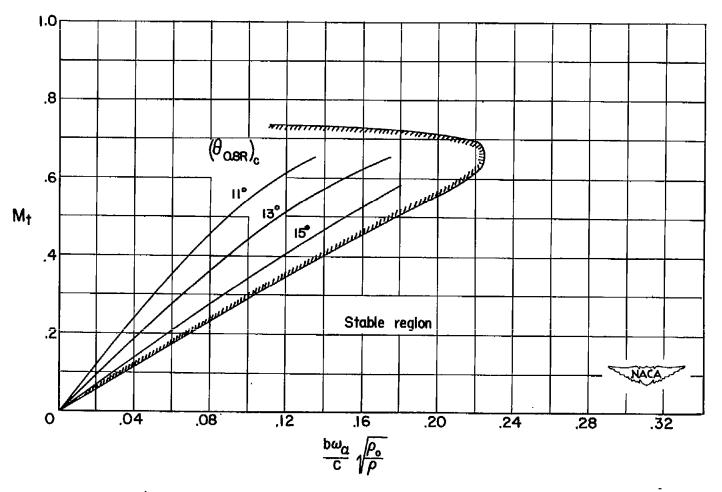


Figure 14.- The effect of the flutter parameter on the tip Mach number at flutter at various pitch angles for blade 2(r).

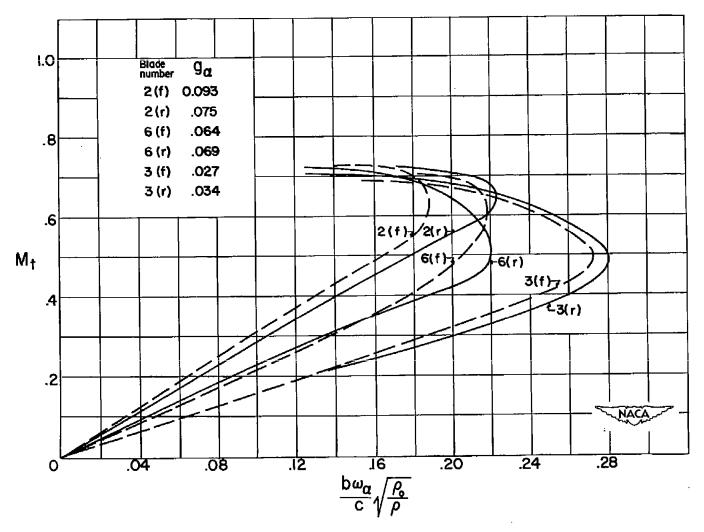


Figure 15.- The envelope flutter boundaries plotted in terms of the tip Mach number and flutter parameter for various blades having different airfoil sections, chordwise center-of-gravity locations, and structural damping coefficients.

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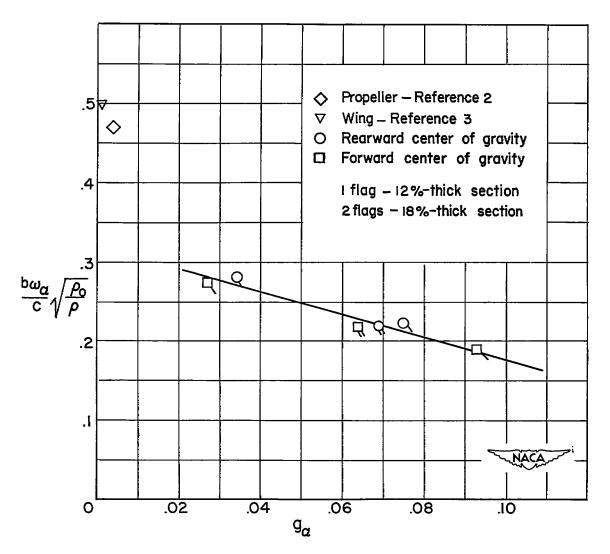


Figure 16.- The variation of critical values of the design flutter parameter with torsional damping.

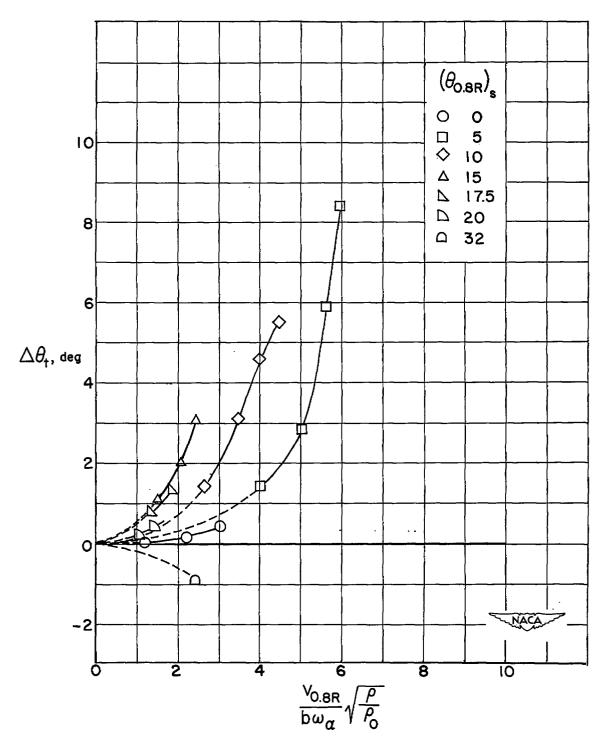


Figure 17.- Measured twist as a function of flutter speed coefficient at various pitch-angle settings for blade 3(r). M $_{\rm t}$ < 0.43.

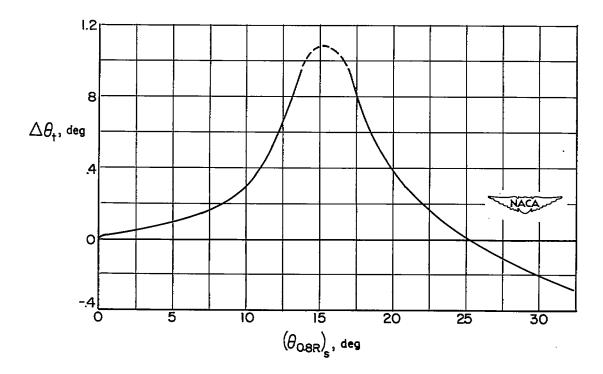


Figure 18.- Measured twist as a function of pitch-angle setting for blade 3(r). Data taken from figure 17 for $(V_0.8R/bu\alpha)(\sqrt{\rho/\rho_0}) = 1.4$.

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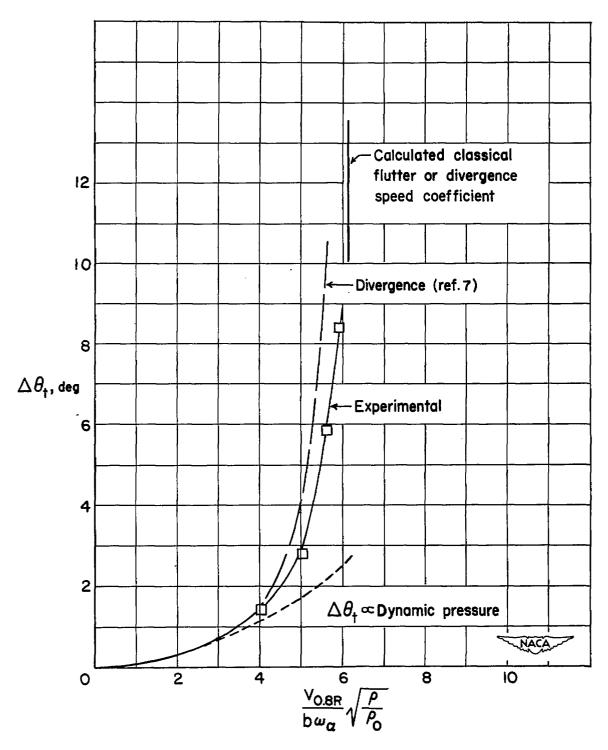


Figure 19.- A comparison between the experimental and calculated effect of the flutter speed coefficient on blade twist as the classical flutter or divergence speed is approached for blade 3(r). $(\theta_{0.8R})_s = 5^{\circ}$.

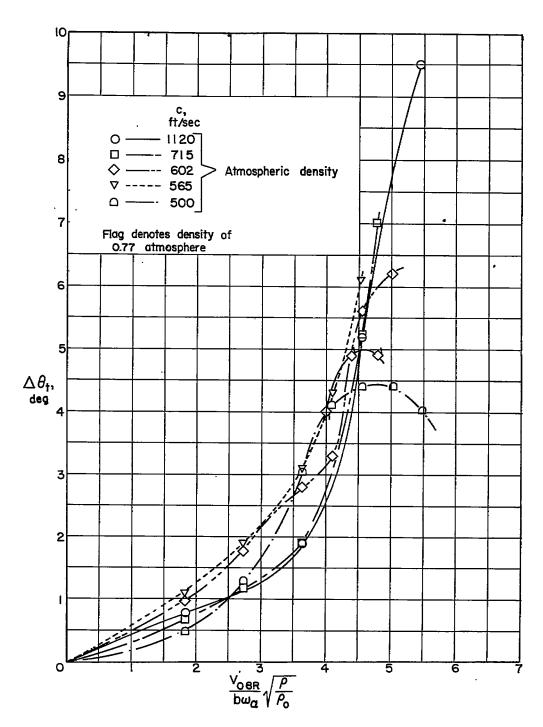


Figure 20.- The effect of the flutter speed coefficient on twist at the tip of blade 4(r) being rotated in mediums of different sound speeds. $(\theta_{0.8R})_{s} = 5^{\circ}$.

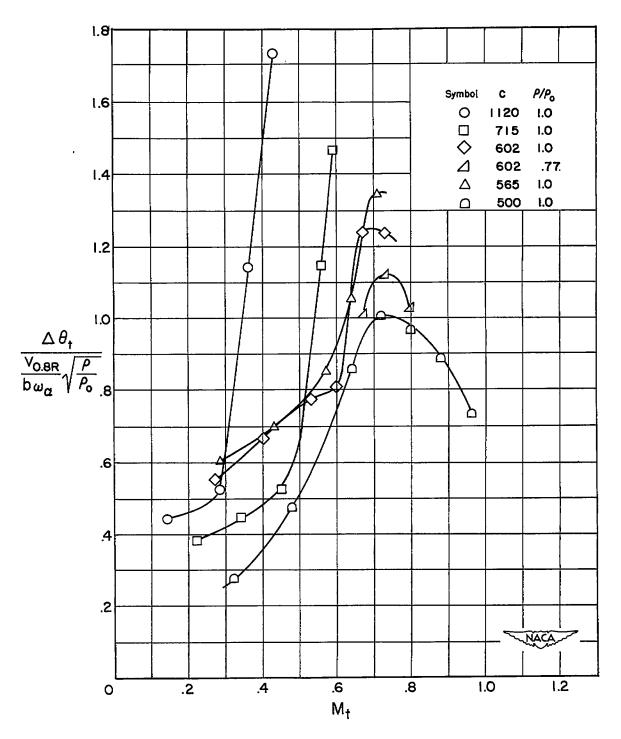


Figure 21.- The effect of blade divergence and Mach number on the measured twist at the tip of blade 4(r) being rotated in mediums at different sound speeds. $(\theta_{0.8R})_s = 5^\circ$.